

NetSim[®]

Accelerate Network R & D

UWAN

Underwater Acoustic Networks

A Network Simulation & Emulation Software

By



The information contained in this document represents the current view of TETCOS LLP on the issues discussed as of the date of publication. Because TETCOS LLP must respond to changing market conditions, it should not be interpreted to be a commitment on the part of TETCOS LLP, and TETCOS LLP cannot guarantee the accuracy of any information presented after the date of publication.

This manual is for informational purposes only.

The publisher has taken care in the preparation of this document but makes no expressed or implied warranty of any kind and assumes no responsibility for errors or omissions. No liability is assumed for incidental or consequential damages in connection with or arising out of the use of the information contained herein.

Warning! DO NOT COPY

Copyright in the whole and every part of this manual belongs to TETCOS LLP and may not be used, sold, transferred, copied or reproduced in whole or in part in any manner or in any media to any person, without the prior written consent of TETCOS LLP. If you use this manual you do so at your own risk and on the understanding that TETCOS LLP shall not be liable for any loss or damage of any kind.

TETCOS LLP may have patents, patent applications, trademarks, copyrights, or other intellectual property rights covering subject matter in this document. Except as expressly provided in any written license agreement from TETCOS LLP, the furnishing of this document does not give you any license to these patents, trademarks, copyrights, or other intellectual property. Unless otherwise noted, the example companies, organizations, products, domain names, e-mail addresses, logos, people, places, and events depicted herein are fictitious, and no association with any real company, organization, product, domain name, email address, logo, person, place, or event is intended or should be inferred.

Rev 15.0, Mar 2026, TETCOS LLP. All rights reserved.

All trademarks are property of their respective owner.

Contact us at

TETCOS LLP

214, 39th A Cross, 7th Main, 5th Block Jayanagar,

Bangalore - 560 041, Karnataka, INDIA.

Phone: +91 80 26630624

E-Mail: sales@tetcos.com

Visit: www.tetcos.com

Contents

1	Introduction	4
2	Simulation GUI	5
2.1	Create Scenario	5
2.2	Devices specific to NetSim UWAN Library	6
2.3	Placement of devices on the grid environment	6
2.4	Enable Packet Trace, Event Trace (Optional)	6
2.5	Enable protocol specific logs and plots	6
2.6	GUI Configuration Parameters	7
3	Model Features	8
3.1	Acoustic PHY	9
3.1.1	Speed of sound	9
3.1.2	Transmit power and Source Level	9
3.1.3	Transmission Losses: Thorp Propagation model	10
3.1.4	Noise	11
3.1.5	Passive Sonar equation	11
3.1.6	MCS, Bit error rate (BER) and Packet error rate	11
3.1.7	Data Rate	12
3.1.8	Collisions, Interference and Packet Capture	12
3.2	MAC Layer	12
3.2.1	Slotted Aloha	13
3.2.2	Slot Length	13
3.2.3	Retry count and Back-off	14
3.3	IP Addressing, Routing, Queuing and Buffers	14
3.3.1	Multi hop communication	14
3.3.2	Queuing and Buffers	14
3.4	Underwater Applications (Network Traffic Generation)	14
3.5	Acoustic Measurements Log	15
3.6	Energy Model in UWAN	16
3.6.1	Energy Calculation	17
4	Featured Examples	17
4.1	Throughput and delay variation with distance	17
4.2	Underwater propagation losses and device range	23
4.3	s-Aloha performance with multiple transmit nodes	27
4.4	Energy consumption analysis in underwater acoustic networks under varying traffic loads	30
4.4.1	Introduction	30
4.4.2	Network setup	31
4.4.3	Simulation results	34
4.4.4	Throughput and Packet collision count	37
5	Limitations	42
6	References	43

1 Introduction

Water covers 71% of the Earth. Underwater communication is essential for a wide assortment of applications covering defence, environmental monitoring, commercial exploration, and scientific discovery. Severe attenuation in water limits the range of electromagnetic, optical and magnetic induction-based communications to just a few meters, leaving acoustic communications as the de facto means for wireless data transfer across tens of kilometers.

NetSim’s UWAN library enables users to design, simulate and analyze performance of underwater networks that use acoustic communication.

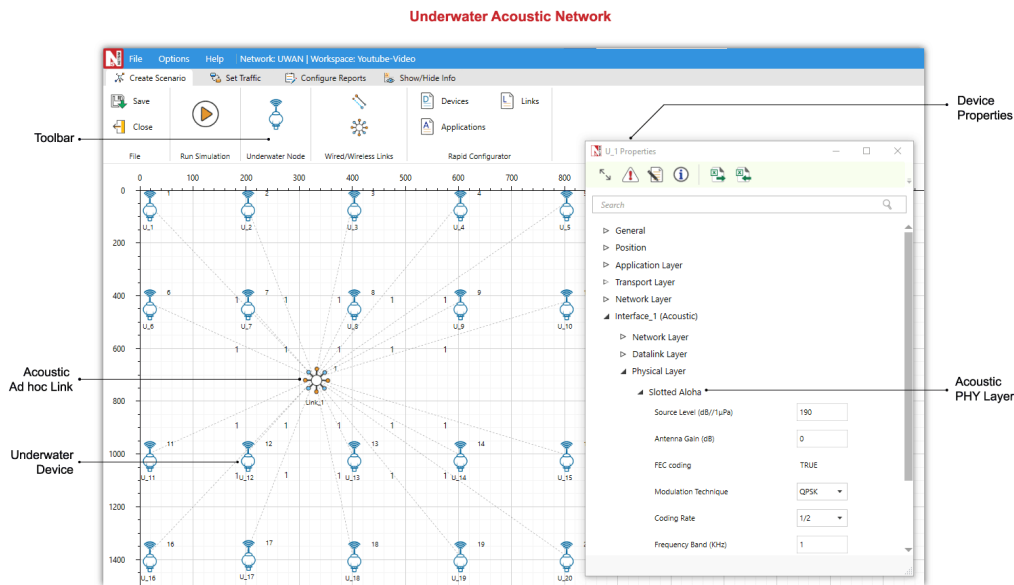


Figure 1-1: Underwater Acoustic Network in NetSim GUI showing the network setup, device properties, and acoustic PHY layer configuration.

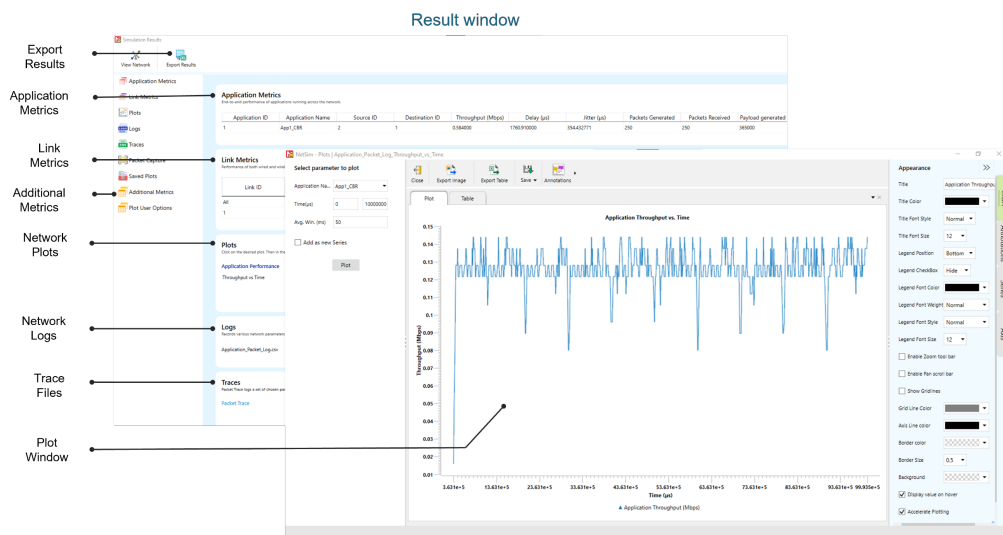


Figure 1-2: NetSim Design Window and the Result dashboard and Plot window shown in NetSim after completion of simulation.

NetSim UWAN simulations are full stack with all 5 layers of the TCP/IP stack being supported as explained below:

- L5, Application: Users can model various kinds of applications as explained in section 3.4. This library supports a new (and default) underwater sensor application - with small packet sizes (order of 10s of Bytes), and large inter-packet arrival times (orders of seconds) - that parallels typical underwater applications.
- L4, Transport: UDP Protocol is supported. TCP is not provided as an option since it is not used in UWAN applications, due to the very low communication bit rates and the high propagation delays.
- L3, Network: Static routing is supported.
- L2, Data Link: Slotted-aloha protocol is supported.
- L1, Physical: Specialized underwater acoustic PHY model and the Thorp propagation model, are supported. Omni directional antennas are assumed.

UWAN is architected to interface with NetSim component 2 (Legacy networks) which provides L2 functionality and component 3 (Advanced switching and routing) which provides the L3 static routing functionality.

The UWAN library is available as Component 12 and is currently available only in NetSim Standard and NetSim Pro versions. Protocol source C code is open to users; it is modular and customizable to help researchers to design and test their own UWAN protocols.

2 Simulation GUI

2.1 Create Scenario

Open NetSim and click New Simulation > Underwater Acoustic Networks as shown in Figure 2-1.

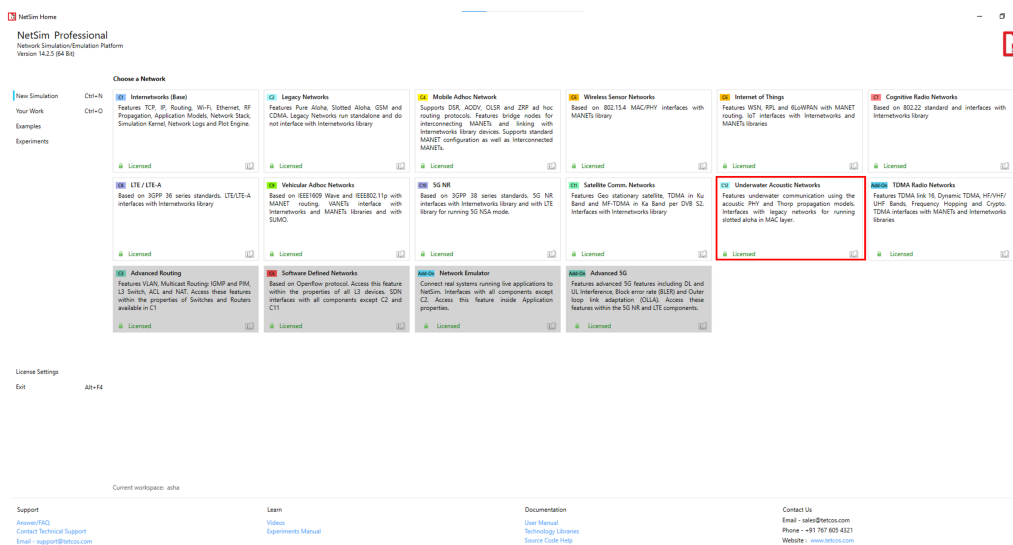


Figure 2-1: NetSim Home Screen

2.2 Devices specific to NetSim UWAN Library

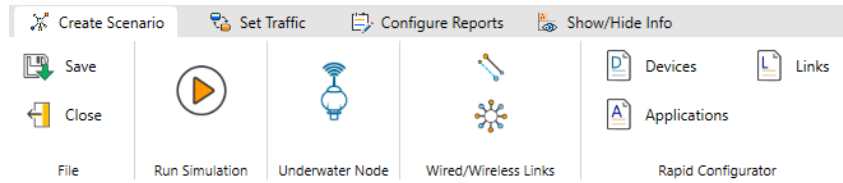


Figure 2-2: The Devices present in the ribbon of NetSim GUI

2.3 Placement of devices on the grid environment

Add an Underwater Device - Click on the Underwater Device icon on the toolbar and place the device in the grid.

2.4 Enable Packet Trace, Event Trace (Optional)

Check Packet Trace / Event Trace option from the Configure Reports tab. To get detailed help, please refer to sections 8.4 and 8.5 in User Manual.

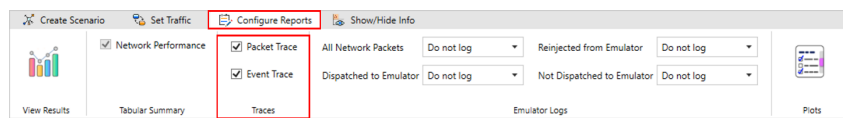


Figure 2-3: Enable Packet Trace, Event Trace & Plots options on top ribbon.

2.5 Enable protocol specific logs and plots

NetSim provides protocol-specific logs for UWAN libraries, which users can enable before running a simulation. These can be enabled by clicking on configure reports in top ribbon > clicking on plots > choosing as desired and running the simulation.

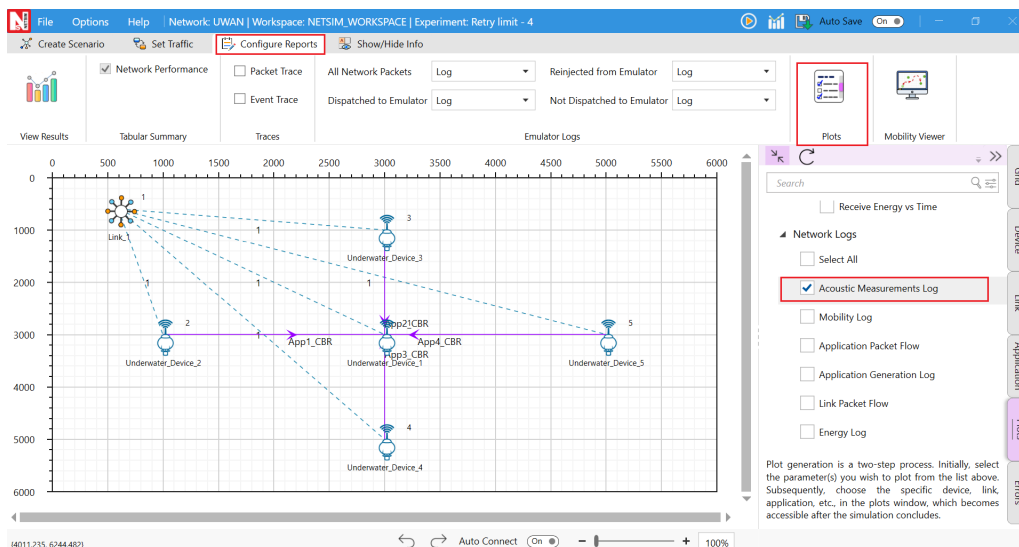


Figure 2-4: Enabling Acoustic Measurements log

Similarly, users can enable the plots for Acoustic Measurements and energy.

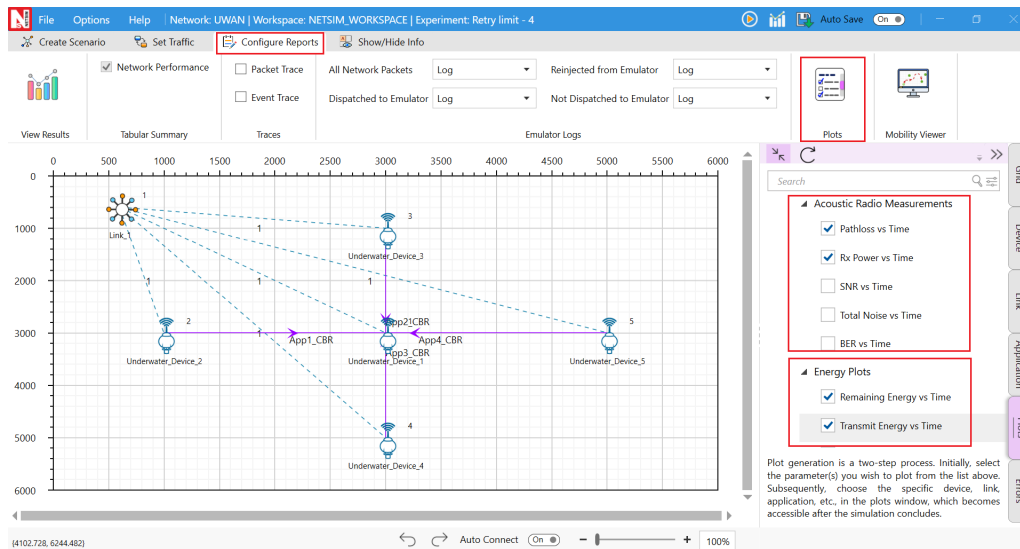


Figure 2-5: *Enabling the plots for UWAN*

2.6 GUI Configuration Parameters

The UWAN parameters can be accessed by right clicking on an Underwater device > selecting Open properties as new window > Interface (Acoustic) Properties → Physical Layers.

Table 2-1: *UWAN Config Properties*

UWAN Properties				
Interface (Acoustic) – Physical Layer				
Parameter	Type		Range	Description
Source Level		Local	170–225 dB// 1 μ Pa, Default: 190 dB// 1 μ Pa	It is the signal level of the transmitter. NetSim GUI takes source level, <i>SL</i> , as the input, with units dB// 1 μ Pa. In seawater, 1 W of radiated acoustic power creates a sound field of intensity 170.8 dB// 1 μ Pa, 1m away from the source. For converting from electrical transmit power, in Watts (W), to <i>SL</i> in dB// 1 μ Pa, the following equation can be used: $SL = 10 \log_{10}((\xi \times P_{tx}^{el})[W]) + 170.8$
Antenna (dBi)	Gain	Local	–1000 to 1000 dBi	A relative measure of an antenna’s ability to direct or concentrate radio frequency energy in a particular direction or pattern. The measurement is typically measured in dBi.
Forward error correction (FEC)	error coding	Fixed	TRUE	FEC is used for controlling Error-Correcting code, in data over unreliable or noisy communication channels. This is always set to true and the SNR BER calculations factor in FEC.
Modulation		Local	QPSK, BPSK, FSK, 16QAM, 64QAM, 256QAM	Modulation is the process of varying one waveform in relation to another waveform. It is used to transfer data over an analog channel.
Coding Rate		Local	1/2, 2/3, 3/4, 5/6	It states what portion of the total amount of information is useful (non-redundant). This code rate is typically a fractional number.
Frequency		Local	0.01–1000 kHz	The center frequency in the transmission bandwidth
Data rate (kbps)		Local	0–255 kbps	It is the number of kilo-bits that are conveyed or processed per second
Receiver Sensitivity (dB)		Local	–120 – 0 dBm, Default: –85 dBm	It is the lowest power level at which the receiver can detect the acoustic signal and demodulate data. The interference threshold is equal to the receive sensitivity as explained in 3.1.8
Bandwidth (Hz)		Local	0–1000 Hz	Bandwidth is the range of frequencies occupied by acoustic signals.

3 Model Features

3.1 Acoustic PHY

Underwater acoustic channels are generally recognized as one of the most difficult communication media in use today. The worst properties of radio channels - poor link quality, and high latency - are combined in the acoustic channel. Acoustic propagation is best supported at low frequencies and is characterized by two major factors: attenuation that increases with signal frequency, and the low speed of sound (≈ 1500 m/s).

3.1.1 Speed of sound

The propagation delay model is complex due to the dependency of the speed of sound on the depth of the water. The speed of sound in water, in meters per second, is given by the formula [1].

$$c_{sound} = 1449.05 + 45.7t - 5.21 \times t^2 + 0.23 \times t^3 + (1.333 - 0.126t + 0.009 \times t^2)(S - 35) + 16.3 \times z + 0.18 \times z^2 \quad (1)$$

Where t is one-tenth of the temperature of the water in degrees Celsius, z is the average depth in km of the temperature zone and S is the salinity of the water in parts per thousand.

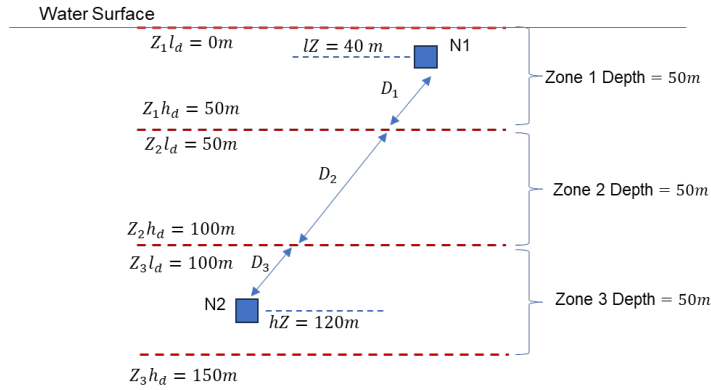


Figure 3-1: An illustration of temperature zones in NetSim where sensor N1 is in zone 1 and sensor N2 is in zone 3.

In the figure, l_d denotes the starting depth and h_d denotes the ending depth of each zone. The zone count (three in this case) and the depth of each zone can be set in NetSim. The average depth in Zone 1 is $\frac{Z_1 l_d + Z_1 h_d}{2} = \frac{0+50}{2} = 25m$, in Zone 2 is $\frac{Z_2 l_d + Z_2 h_d}{2} = \frac{50+100}{2} = 75m$, and in zone 3 is $\frac{Z_3 l_d + Z_3 h_d}{2} = \frac{100+150}{2} = 125m$. The propagation delay is computed separately as

$$\Delta_{tot} = \Delta_1 + \Delta_2 + \Delta_3 = \frac{D_1}{C_{sound}^{zone1}} + \frac{D_2}{C_{sound}^{zone2}} + \frac{D_3}{C_{sound}^{zone3}} \quad (2)$$

3.1.2 Transmit power and Source Level

An acoustic signal propagates as a pressure wave, whose power is measured in Pascals (commonly, in dB relative to a micro-Pascal). NetSim GUI takes source level, SL , as the input, with units $dB//1\mu Pa$. We may think of $dB//1\mu Pa$ in acoustics as playing the role of dBm in RF. When referring to the Tx/Rx (acoustic) power it is customary to specify the acoustic intensity value in decibel (dB) relative

to the intensity due to 1 micro-pascal (μPa) root mean square (RMS) pressure. In seawater, 1 W of radiated acoustic power creates a sound field of intensity 170.8 dB//1 μPa , 1m away from the source. For converting from electrical transmit power, P_{tx}^{el} in Watts (W), to SL in dB//1 μPa , the following equation can be used

$$SL = 10 \log_{10}((\xi \times P_{tx}^{el})[W]) + 170.8 \quad (3)$$

where ξ is transducer efficiency. The 170.8 dB accounts for the conversion between dB//1 μPa and W. Given below in Table 3-1 are the properties of six commercial and research underwater modems. SL is computed assuming $\xi = 1$.

Table 3-1: Commercial underwater modems and their specifications

Underwater modem	P_{tx}^{el} (W)	SL (dB)	BW (kHz)	Rate (kbps)
EvoLogics S2CR 18/34 WiSE	35	186.2407	26	13.90
WHOI Micromodem	48	187.6124	25	5
Teledyne Benthos ATM9XX	20	183.8103	24.50	15.36
LinkQuest UWM4000	7	179.251	17	8.50
Aquatech AQUAModem 1000	20	183.8103	9.75	2
DSPComm AquaComm Marlin	1.8	173.3527	23	0.48

3.1.3 Transmission Losses: Thorp Propagation model

A distinguishing property of acoustic channels is the fact that path loss depends on the signal frequency. This dependence is a consequence of absorption (i.e., transfer of acoustic energy into heat). The simplest model for acoustic attenuation in water is

$$A(d, f) = d^k \alpha(f)^d \quad (4)$$

Where α : absorption coefficient factor, depends on the sound frequency f , d : Distance, and k : the spreading coefficient defined by geometry. The spreading factor, k , describes the geometry of propagation and is typically $1 \leq \alpha \leq 2$, e.g., $k = 1$, and $k = 2$ correspond to cylindrical and spherical spreading, respectively. $k = 1.5$ is often considered a practical setting. A cylindrical spreading corresponds to cases in which the transmission distance l is much larger than the depth of the ocean. In this case, the ocean bottom and the interface between the ocean and the air act as boundaries for the spreading of acoustic waves. On the other hand, spherical spreading is considered when the transmission distance is smaller than the depth of the ocean. This type of spreading provides a similar k as the free-space approximation for radio wireless communications.

A common empirical formula used for absorption $\alpha(f)$ is Thorp's formula, which for f in kHz is given by

$$10 \log_{10}(\alpha(f)) = \begin{cases} 0.11 \times \frac{f^2}{1 + f^2} + 44 \times \frac{f^2}{4100 + f^2} + 2.75 \times 10^{-4} \times f^2 + 0.003 & f \geq 0.4 \\ 0.002 + 0.11 \times \frac{f^2}{1 + f^2} + 0.011 \times f^2 & f < 0.4 \end{cases} \quad (5)$$

This output is in dB/km. Combining absorption effects and spreading loss, the total attenuation is as follows:

$$10 \log A(d, f) = k \times 10 \log(d_m) + d_{km} \times 10 \log \alpha(f) \quad (6)$$

Here d_m is the distance in meters, $d_{km} = \frac{d_m}{1000}$, and f is in kHz . The Thorp model outputs the attenuation in dB.

3.1.4 Noise

The calculation for the ambient noise in the underwater environment is divided into the major factors contributing to the total: turbulence, shipping, wind, and thermal. The following formulae give the noise power [dB] of the four components

$$10 \log N_t(f) = 17 - 30 \log(f) \quad (7)$$

$$10 \log N_s(f) = 40 + 20 \times (s - 0.5) + 26 \log f - 60 \times \log(f + 0.03) \quad (8)$$

$$10 \log N_w(f) = 50 + 7.5 \times \sqrt{w} + 20 \log f - 40 \log(f + 0.4) \quad (9)$$

$$10 \log N_{th}(f) = -15 + 20 \log f \quad (10)$$

Where f is frequency in kHz, s is the shipping factor and w is the wind-speed in m/s . The default value for s is 0.5 and for w is 0.

Turbulence noise influences only the very low frequency region, $f < 10Hz$. Noise caused by distant shipping is dominant in the frequency region $10Hz - 100Hz$, and it is modeled through the shipping activity factor s , whose value ranges between 0 and 1 for low and high activity, respectively. Surface motion, caused by wind-driven waves (w is the wind speed in m/s) is the major factor contributing to the noise in the frequency region $100Hz - 100kHz$ (which is the operating region of most acoustic systems). Finally, thermal noise becomes dominant for $f > 100$ kHz.

The total noise in linear scale is given as

$$N_{total}^{linear} = N_t^{linear} + N_s^{linear} + N_w^{linear} + N_{th}^{linear} \quad (11)$$

and the total noise in dB domain is $N_{dB}^{total}[dB] = 10 \log_{10}(N_{total}^{linear})$

3.1.5 Passive Sonar equation

NetSim uses the passive sonar equation to compute the SNR at the receiver. The passive sonar equation is written as

$$SNR = SL - TL - (NL - DI) \quad (12)$$

Where SL is the source level, TL is the transmission losses, NL is the noise level and DI is receiver directivity index. NetSim assumes $DI = 0$, and upon appropriate substitutions the equation turns out as

$$SNR [dB] = SL - 10 \log_{10}(A(d, f)) [dB] - N_{dB}^{total} [dB] \quad (13)$$

On the RHS of the equation, the second term is TL and the final term is the NL .

3.1.6 MCS, Bit error rate (BER) and Packet error rate

Unlike 802.11 or 5G protocols, there are no standards specifying the modulation and coding scheme (MCS) for different received signal powers. Hence MCS is a user settable input parameter. Bit-error-rate (BER) is computed from the received signal to noise ratio (SNR) and the modulation and coding scheme (MCS) set by the user. NetSim assumes that the noise variance is Gaussian and computes BER using theoretical formulas for each modulation scheme. The energy per bit to noise spectral density ratio (E_b/N_0) is first derived from the SNR, adjusted for the ratio of data rate to bandwidth:

$$\frac{E_b}{N_0} = SNR_{linear} \times \frac{\text{Data Rate}}{\text{Bandwidth}} \quad (14)$$

Packet error rate (PER) is then calculated from BER based on packet length as follows:

$$PER = 1 - (1 - BER)^{L_{bits}} \quad (15)$$

where L_{bits} is the total packet length in bits.

Users who wish to use their own (custom) SNR-BER tables can modify the UWAN_Calculate_BER function in UWAN.c file under the UWAN project.

3.1.7 Data Rate

The data rate is set through a GUI parameter; it is not computed by NetSim during simulation. In NetSim, the modulation and coding scheme (MCS) is set by the user in the GUI. This MCS setting does not affect the data rate; it only impacts BER calculations. More information on MCS is provided in section 3.1.6. The implicit assumption is that the user sets the right combination of data rate and MCS.

3.1.8 Collisions, Interference and Packet Capture

Per conventional definition, collisions occur when there is simultaneous packet transmission, and these collided packets are assumed failed or lost. In this characterization, when there is simultaneous packet transmission, collisions are assumed to occur whatever the spatial separation (distance) between nodes and whatever the nodes' transmit powers. Clearly this is an approximation aimed at simplification. In case of simultaneous packet transmissions, it is possible that one (or more) signals have sufficient strength to be decoded by the receiver. Therefore, packets involved a collision can sometimes be successfully received. This phenomenon is known as Packet Capture.

NetSim approximately models Packet Capture considering interference threshold (I_{th}) rather than SINR. To elaborate, we start by denoting Underwater device as UWD and let UWD_{tx} be transmitting a packet to UWD_{rx} , while UWD_I^n be n other $UWDs$ that are transmitting at the same time. These are marked with subscript I since these transmissions would interfere with the UWD_{tx} to UWD_{rx} transmission. NetSim computes the total received power at UWD_{rx} from all simultaneously transmitting $UWDs$, including UWD_{tx} . The interference power is then obtained by subtracting the desired signal power (from UWD_{tx}) from the total received power. That is, the interference is $\sum_{j=1}^n P_r^j$ where P_r^j is the received power of interfering UWD_I^j at UWD_{rx} , excluding the power of the desired signal. This interference power is compared against an interference threshold I_{th} which is equal to the receive sensitivity (set to $-85dB$ by default in NetSim). If the interference power is greater than the interference threshold, then the packet being transmitted from UWD_{tx} to UWD_{rx} is marked as collided. Should the interference power be less than $-85dB$, the packet being transmitted from UWD_{tx} to UWD_{rx} is successfully received at UWD_{rx} .

An exact SINR based packet capture model (rather than the approximate interference threshold-based packet capture model) is under development.

3.2 MAC Layer

NetSim currently only supports slotted Aloha in the MAC layer.

The reason for not supporting a contention-based protocol is: the basic principle of carrier sensing multiple access — that a node should transmit only if it hears no ongoing transmissions — is compromised in an acoustic channel where the packets propagate slowly, and the fact that none are overheard does not mean that some are not present in the channel.

3.2.1 Slotted Aloha

NetSim UWAN stack runs slotted Aloha (s-Aloha) in the MAC layer. s-Aloha is decentralized medium access control protocol that does not perform carrier sensing. Data transmission by devices is synchronized to timeslots. All devices are assumed to be perfectly synchronized to one another and to the timeslots.

In NetSim’s s-Aloha implementation, the transmitter sends the next packet only after the current packet has either been received or errored. The knowledge of a packets successful or erroneous reception (due to collision or channel error) is known by the receiver only after it receives the complete packet. In case of unicast applications, the total time taken for the reception of a packet after the transmission commences is equal to the transmission time T_{tx} plus the propagation delay Δ . It is assumed in NetSim, that the transmitter knows packet status at the exact time that the receiver knows the packet status. Hence the transmitter gets to know if a packet is successful or errored only $(T_{tx} + \Delta)$ seconds after commencing transmission. If the packet is errored the transmitter will retransmit (depending on the retry count set by the user in the UI) the packet; if the packet is successful, the transmitter will send the next packet.

3.2.2 Slot Length

Due to the long propagation delays user should take care to set the slot size in the GUI. This is a global parameter applicable to all UWAN devices. As a starting step, estimate the transmission time, T_{tx} which would be

$$T_{tx} (\mu s) = \frac{(L_{pkt} + OH) \times 8}{PHYRate} \quad (16)$$

where L_{pkt} is the application layer packet size, OH is the overheads of all layers which is equal to 28B, and $PHYRate$ is the data rate set in the PHY layer. Next, the propagation delay, Δ is computed as $\Delta = \frac{d}{c_{sound}}$, where d is the distance between the transmitter and the receiver. Thus, the ideal slot length should be

$$L_{slot} = \frac{(L_{pkt} + OH) \times 8}{PHYRate} + \frac{d}{C_{sound}} \quad (17)$$

Example: Let us consider the default values of $L_{pkt} = 14B$ and $PHYRate = 20 Kbps$ which leads to $T_{tx} = 16,800 \mu s$. Then using $t = \frac{25}{10} = 2.5$, $z = 50$, and $S = 35$ - where t is one-tenth of the temperature of the water in degrees Celsius, z is the depth in meters and S is the salinity of the water - we get (per earlier section 3.1) $c_{sound} = 2799.33 m/s$. When the transmitter receiver distance is $d = 2km$, the propagation delay, $\Delta = \frac{2 \times 10^3}{2799.33} = 714,456.4 \mu s$. Substituting all these, we see that the ideal slot length (when $d = 2km$) would be

$$L_{slot} = T_{tx} + \Delta = 16,800 + 714,456.4 = 731,256.4 \mu s = 0.73 s \quad (18)$$

Considering a slot length of $731,256.4 \mu s$, we see if one packet exactly fits one slot then the predicted saturation throughput would be

$$\theta_{sat} = \frac{(L_{pkt} \times 8)}{L_{slot}} = \frac{(14 \times 8)}{731256.4 \times 10^{-6}} = 153 \text{ bps} \quad (19)$$

NOTE:

- If different Tx-Rx pairs are at different distances, then users should set the slot length based on the largest Tx-Rx distance i.e., based on the largest propagation delay.
- NetSim limitation of not modeling link-level (reverse) ACKs can be overcome by adding additional time in the slot length to account for ACK transmissions. This work around, however, does not account for ACK failures.

3.2.3 Retry count and Back-off

An important MAC layer parameter is Retry Count. This is a user-configurable parameter. A transmitter running s-Aloha retries when packets received (at the receiver) are in error. Recall here the NetSim assumption that the transmitter knows the packet status at the receiver.

The maximum number of times the transmitter retries is equal to Retry Count. Once this limit is hit the transmitter drops the packet. For example, if the Retry Count is 3, and if a packet fails in 1st transmission and in the 1st, 2nd and 3rd retransmission, then that packet is dropped by the transmitter.

The transmitter backs-off before each retry. The back off time (in slots) is a random number chosen from $[0, CW - 1]$ where CW is the contention window and is equal to 2^n , where n is the current value of the Retry Count. Unlike the 802.11 protocols, in s-Aloha, the transmitter does not back off before the 1st transmission.

The description above pertains to the behavior of unicast packets. For broadcast applications, the procedure varies as follows:

- Prior to the first transmission, the transmitter implements a back-off. The duration of this back-off is randomized, selected from a range of 0 to 7 slots.
- Broadcast packets do not undergo re-transmissions.

3.3 IP Addressing, Routing, Queuing and Buffers

Addressing for UWAN devices is IP based. The IP addresses are automatically set by NetSim.

3.3.1 Multi hop communication

The fact that the acoustic bandwidth depends on the distance has important implications for the design of underwater networks. Specifically, it makes a strong case for multihopping, since dividing the total distance between a source and destination into multiple hops enables transmission at a higher bit rate over each (shorter) hop.

NetSim currently supports static routing for multi-hop communication. Ad hoc routing is not yet available. While, no routing configuration is required for single hop communication, static routing needs to be configured for multi-hop communication. Static routing configuration is explained in the Internetworks technology library manual, Section: Configuring Static Routing in NetSim.

3.3.2 Queuing and Buffers

Queuing in UWAN devices is on a first-in-first-out (FIFO) basis. For example, if a UWAN device is acting as both a source of traffic and a relay, then source traffic and relay traffic would arrive at the device's (MAC) buffer. The traffic would be queued and served per FIFO working. UWAN devices in NetSim have infinite (MAC) buffers.

3.4 Underwater Applications (Network Traffic Generation)

Users can model various kinds of applications (that generate network traffic). These include CBR, File transfer, Video etc. Typical examples of transfers from one underwater device to another include (i) transferring a file (ii) transmitting very low bit rate video (iii) generating a constant-bitrate (CBR) application for theoretical performance studies etc. Details of the different application models are provided in Section 6 of the NetSim user manual.

3.5 Acoustic Measurements Log

NetSim Acoustic Measurements Log csv file records pathloss, distance, transmitted power, received power, total noise, SNR, BER etc. This log can be used to understand the effects of the acoustic propagation model and the impact of varying channel conditions.

This log file can be enabled from the Configure report tabs > Plots > Acoustic measurements log as explained in section 2.5.

The Acoustic Measurements Log.csv file will contain the following information:

- Time in milliseconds
- Transmitter Name
- Receiver Name
- Distance between transmitter and receiver in meters.
- Transmitter Power in dB/ μ Pa
- Pathloss in dB/ μ Pa
- Total Noise in dB/ μ Pa
- SNR in dB
- Receiver Power in dB/ μ Pa
- BER

The log file can be accessed from the Simulations Results Window by clicking Logs option in the left pane.

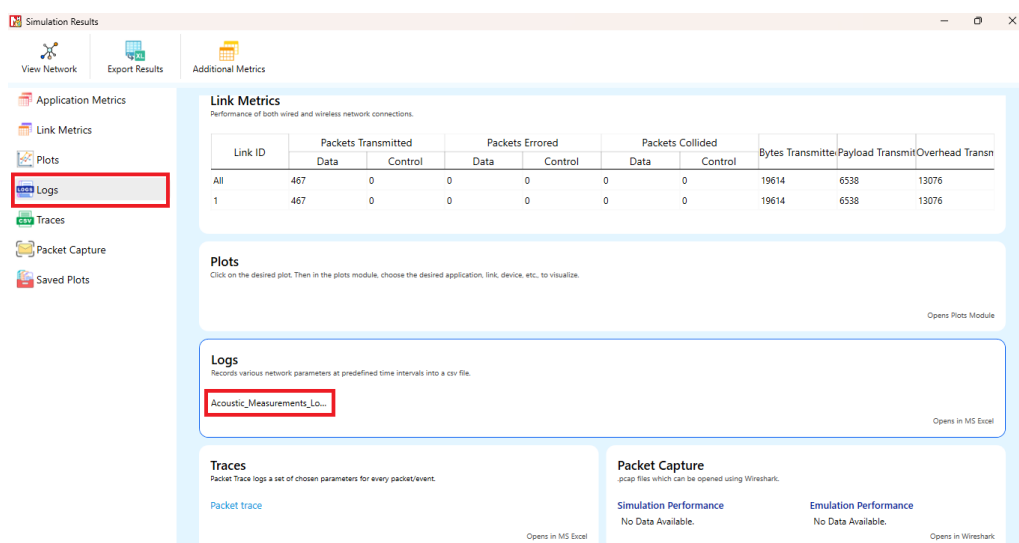


Figure 3-2: Acoustic Measurements Log.csv file highlighted in the Results window.

Time(ms)	Transmitter Name	Receiver Name	Distance(m)	Tx Power(dB/1 micro Pa)	Pathloss(dB/1 micro Pa)	Total Noise(dB/1 micro Pa)	SNR(dB)	Rx Power(dB/1 micro Pa)	BER
127.141435	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
341.093035	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
555.044635	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
768.996235	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
982.947835	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
1196.899435	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
1410.851035	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
1624.802635	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
1838.754235	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
2052.705835	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
2266.657435	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
2480.609035	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
2694.560635	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
2908.512235	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
3122.463835	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
3336.415435	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
3550.367035	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0
3764.318635	UNDERWATER_DEVICE_1	UNDERWATER_DEVICE_3	308.882226	190	0	45.372625	144.62738	190	0

Figure 3-3: Acoustic Measurements Log.csv file

3.6 Energy Model in UWAN

In UWAN, nodes consume different amounts of energy in each of their modes of operation, namely, sending/transmitting mode, receiving mode, and idle mode.

Transmitting mode: In this mode, nodes consume energy to transfer packets.

Receiving mode: In this mode, nodes consume energy to receive packets.

Idle mode: In this mode, a node neither transmits nor receives data packets. This is typically a low energy mode.

In NetSim, default energy model settings are as follows.

- Initial Energy (mJ): 10416
- Transmitting current (mA): 6250
- Receiving current (mA): 37.5
- Idle mode current (mA): 1.6
- Voltage (V): 48

The power model is disabled by default. It can be enabled in physical layer of an underwater device. Right click on underwater device properties > Interface 1(Acoustic) > Physical layer

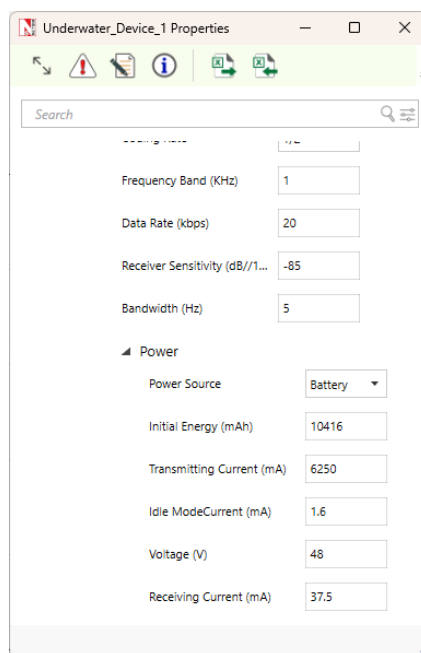


Figure 3-4: Power model in UWAN.

3.6.1 Energy Calculation

The energy calculations for each packet in each mode are given below. This data is logged in NetSim’s energy log file.

$$\text{Transmitting Energy (mJ)} = \frac{V \times I_{mode} \times (t_{current} - t_{switch})}{10^3} \tag{20}$$

$$\text{Receiving Energy (mJ)} = \frac{V \times I_{mode} \times (t_{current} - t_{switch})}{10^3} \tag{21}$$

$$\text{Idle Energy (mJ)} = \frac{V \times I_{mode} \times (t_{current} - t_{switch})}{10^3} \tag{22}$$

where V is Voltage (V), I_{mode} is ModeCurrent (mA), $t_{current}$ is CurrentTime (ms), and t_{switch} is Mod-eSwitchTime (ms).

$$\text{Consumption Energy (mJ)} = \text{Transmitting Energy (mJ)} + \text{Receiving Energy (mJ)} + \text{Idle Energy (mJ)} \tag{23}$$

where current time minus mode-switch-time is the time for which the node is in a particular mode.

4 Featured Examples

4.1 Throughput and delay variation with distance

Open NetSim and Select Examples → Underwater Acoustic Network → Throughput and delay variation with distance and then click on the tile in the middle panel to load the example as Figure 4-1.

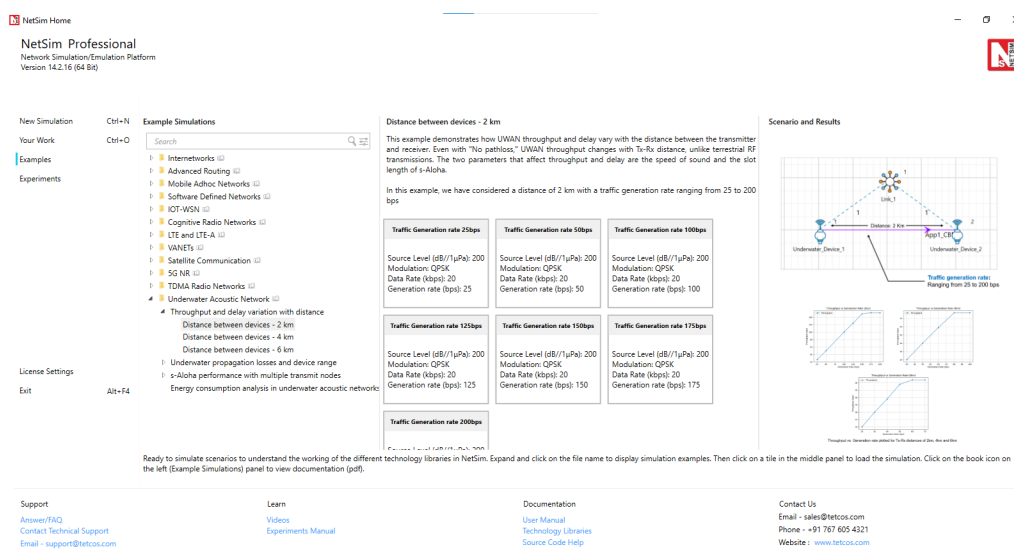


Figure 4-1: List of scenarios for the example of Throughput and delay variation with distance

In this example, we understand how UWAN throughput and delay varies as the distance between 1

transmitter and 1 receiver is varied. Even with no pathloss the throughput in UWAN varies with Tx-Rx distance which is not the case in terrestrial RF based transmissions. The two parameters that affect throughput and delay are the speed of sound and the slot length of s-Aloha. The speed of sound in water is given by the formula

$$c_{sound} = 1449.05 + 45.7t - 5.21 \times t^2 + 0.23 \times t^3 + (1.333 - 0.126t + 0.009 \times t^2) (S - 35) + 16.3 \times z + 0.18 \times z^2 \quad (24)$$

where t is one-tenth of the temperature of the water in degrees Celsius, z is the depth in km and S is the salinity of the water in ppt. Then using $t = \frac{25}{10} = 2.5$, $z = 50$, and $S = 35$ - where t is one-tenth of the temperature of the water in degrees Celsius, z is the depth in meters and S is the salinity of the water - we get $c_{sound} = 2799.33 \text{ m/s}$. When the transmitter receiver distance is $d = 2 \text{ km}$, the propagation delay, $\Delta = \frac{2 \times 10^3}{2799.33} = 714,456.4 \mu\text{s}$

Next, as explained in section 3.2.2, we consider ideal slot lengths for different transmitter receiver distances. In the case when $d_{Rx}^{Tx} = 2 \text{ km}$ the slot length turns out as

$$L_{Slot} = T_{tx} + \Delta = 16,800 + 714,456.4 = 731,256.4 \mu\text{s} = 0.73 \quad (25)$$

Table 4-4 shows the ideal slot length settings for $d_{Rx}^{Tx} = 4 \text{ km}$ and $d_{Rx}^{Tx} = 6 \text{ km}$.

Network setup:

- The following network diagram illustrates what the NetSim UI displays when you open the example configuration file.

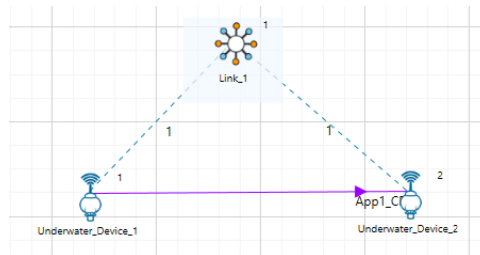


Figure 4-2: Network Scenario. Two underwater devices connected via an acoustic ad hoc link

- In case #1, distance between the underwater devices is set to be 2km. In case #2 the distance is 4km, while in case #3 it is set to 6 km
- Click on link, expand the property panel on the right and set the Channel characteristics as No pathloss.
- Device Configuration:

Table 4-1: Device properties set for this example

Device > Interface (ACOUSTIC) > Datalink Layer	
Slot Length (μs)	731257 for 2 km
Device > Interface (ACOUSTIC) > Physical Layer	
Source Level ()	200
Modulation	QPSK
Data Rate (kbps)	20

Application Configuration:

We run simulations for different traffic generation rates. The generation rate depends on the inter arrival time – a GUI input in NetSim – in the following way

$$\text{Generation Rate (Mbps)} = \frac{\text{Packet Size (Bytes)} \times 8}{\text{Interarrival Time } (\mu\text{s})} \quad (26)$$

Table 4-2: Application properties for the different samples in each case studied in this example

Application Properties	
Application Method	App1 CBR
Source ID	1
Destination ID	2
Packet Size (Bytes)	14
Inter arrival Time (μs)	Generation rate (bps)
Case-1	
4480000	25
2240000	50
1120000	100
896000	125
746666.6666	150
640000	175
560000	200
Case-2	
5600000	20
2800000	40
1866666.6666	60
1400000	80
1120000	100
Case-3	
5600000	20
3733333.333	30
2800000	40
2240000	50
1866666.6666	60
1600000	70

- Enable packet trace and Acoustic Measurements Log under Configure report tab as shown below

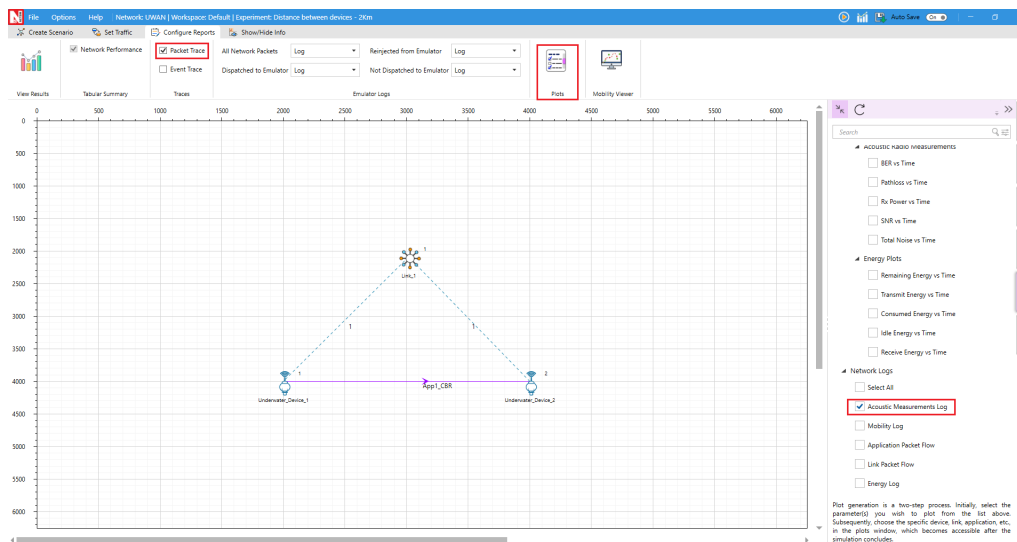


Figure 4-3: Enabling the Acoustic Measurements Log

- Run the Simulation for 100 sec.

Theoretical Predictions

The predicted propagation delay when the speed of sound $c_{sound} = 2799.33 \text{ m/s}$ is

Table 4-3: Theoretically predicted propagation delay for different Tx-Rx distances

Distance between devices	Propagation delay (μs)
2km	714456.4
4km	1428912.7
6km	2143369.1

Transmission delay and Saturation Throughput

Considering a slot length of $731,257 \mu\text{s}$, we see that one packet exactly fits one slot and hence the predicted saturation throughput would be

$$\theta_{sat}^{2km} = \frac{(L_{pkt} \times 8)}{L_{slot}} = \frac{(14 \times 8)}{731256.4 \times 10^{-6}} = 153 \text{ bps} \tag{27}$$

Proceeding similarly for 4 km and 6 km, the predictions for saturation throughput are

Table 4-4: Ideal slot lengths and theoretically predicted saturation throughputs (θ_{sat}) for different Tx-Rx distances.

Distance between devices	Slot Length (μs)	Saturation Throughput (bps)
2 km	731257	153
4 km	1445713	77
6 km	2160170	52

Simulation results

We calculate queuing delay, transmission delay, and propagation delay from the packet trace. The steps are:

- Open Packet Trace file using the Packet Trace option available in the Simulation Results window under traces.
- The difference between the PHY LAYER ARRIVAL TIME(US) and the MAC LAYER ARRIVAL TIME(US) will give us the delay of a packet. (Refer Figure 4-4)

$$\text{Queuing Delay } (\mu s) = \text{PHYSICAL LAYER ARRIVAL TIME}(\mu s) - \text{MAC LAYER ARRIVAL TIME } (\mu s) \quad (28)$$

Figure 4-4: Screen shot of NetSim trace showing the Queuing Delay column

- Now, calculate the mean queuing delay by taking the average of the queuing delays of all the packets. This is nothing but the column average. (Refer Figure 4-4)
- Similarly, users can get the Mean Transmission Delay and Mean Propagation Delay from the packet trace using the formulas

$$\text{Transmission Delay } (\mu s) = \text{PHY LAYER START TIME}(\mu s) - \text{PHY LAYER ARRIVAL TIME}(\mu s) \quad (29)$$

$$\text{Propagation Delay } (\mu s) = \text{PHY LAYER END TIME}(\mu s) - \text{PHY LAYER START TIME}(\mu s) \quad (30)$$

Table 4-5: Tabulated results (throughput and delays) for 3 different Tx-Rx distances.

Case	Gen. Rate (bps)	Thru-put (bps)	Delay (μs)	Mean Prop. Delay (μs)	Mean Tx De-lay (μs)	Mean Queue Delay (μs)
Case #1: Distance between underwater devices is 2km						
	25	26	1113144.78	714456.35	16800	381888.43
	50	50	1111731.73	714456.35	16800	380475.37
	100	100	1094568.64	714456.35	16800	363312.29
	125	124	1091089.64	714456.35	16800	359833.28
	150	149	1116252.45	714456.35	16800	384996.10
	175	152	6891103.855	714456.35	16800	6159847.5
	200	152	12291103.8	714456.35	16800	11559847.5
Case #2: Distance between underwater devices is 4km						
	20	20	2036146.04	1428912.7	16800	590433.33

Case	Gen. Rate (bps)	Thru-put (bps)	Delay (μ s)	Mean Prop. Delay (μ s)	Mean Tx De-lay (μ s)	Mean Queue Delay (μ s)
	40	40	2081859.04	1428912.7	16800	636146.33
	60	59	2148454.18	1428912.7	16800	702741.47
	80	77	2999954.70	1428912.7	16800	1554242
	100	77	12519954.7	1428912.7	16800	11074242
Case #3: Distance between underwater devices is 6km						
	20	20	3163994.06	2143369.06	16800	1003825
	30	30	3230739.43	2143369.06	16800	1070570.37
	40	39	3194853.63	2143369.06	16800	1034684.57
	50	49	3340415.65	2143369.06	16800	1180246.5
	60	52	8763994.06	2143369.06	16800	6603825
	70	52	14763994.0	2143369.06	16800	12603825

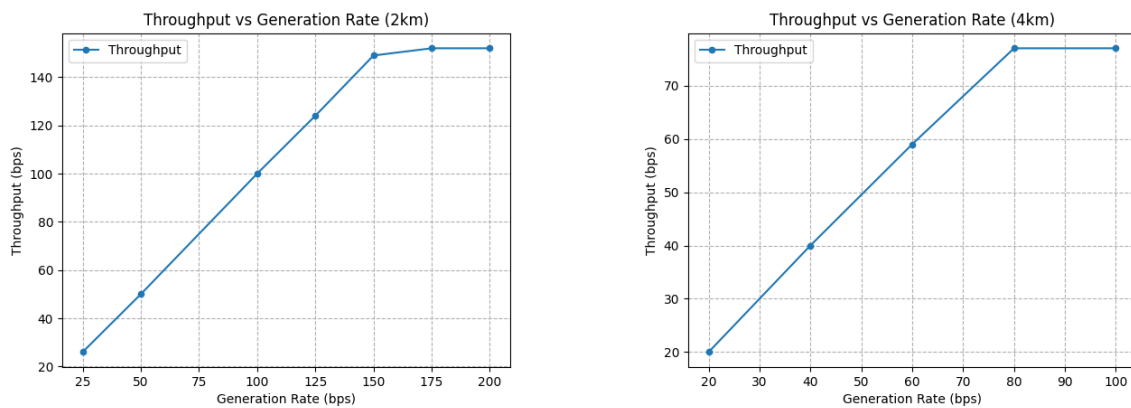


Figure 4-5: Throughput vs. Generation Rate for Tx-Rx distances of 2km (left) and 4km (right).

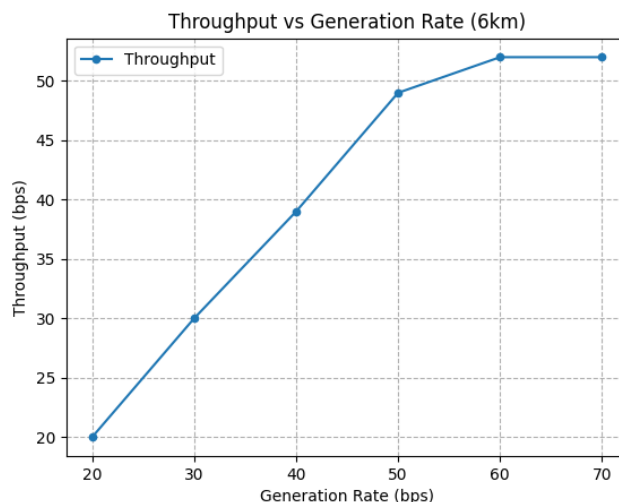


Figure 4-6: Throughput vs. Generation rate plotted for Tx-Rx distances of 2km, 4km and 6km based on earlier tables.

From Table 4-5, we see that the propagation delays from simulation match predictions in Table 4-3. Then we observe that saturation throughput (the Y axis value once the curve flattens) matches prediction.

Table 4-6: *NetSim UWAN Simulation results vs. theoretical prediction of saturation throughput, for different Tx-Rx distances.*

Distance between devices	Saturation Throughput Predicted (bps)	Saturation Throughput Simulation
2 km	153	152
4 km	77	77
6 km	52	52

4.2 Underwater propagation losses and device range

Open NetSim and Select Examples → Underwater Acoustic Network → Underwater propagation losses and device range and then click on the tile in the middle panel to load the example as Figure 4-7.

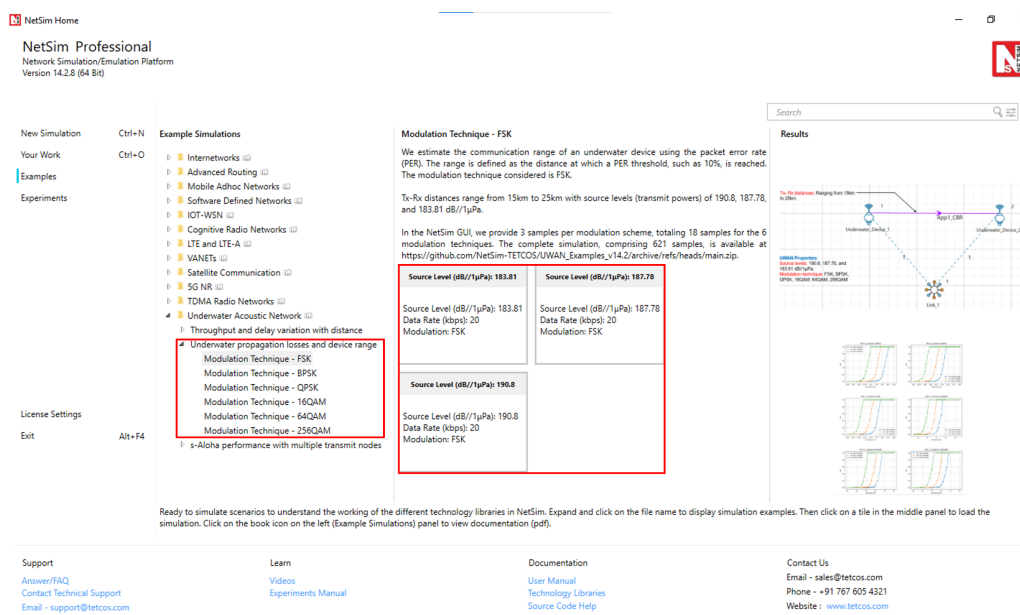


Figure 4-7: *List of scenarios for the example of Underwater propagation losses and device range.*

In this example, we understand the Thorp propagation model, the sources of underwater noise, the passive sonar equation and how device range can be estimated based on received SNR. Refer to section 3.1 for the underlying theory on signal level, transmission losses, and the passive sonar equation.

In the NetSim GUI, we provide 3 samples per modulation scheme, totaling 18 samples for the 6 modulation techniques. The complete set of configuration files (scenario, settings and other related files) comprising of 621 samples, is available at https://github.com/NetSim-TETCOS/UWAN_Examples_v14.4/archive/refs/heads/main.zip.

Click on the link given and download UWAN Experiments

1. Extract the zip folder. The extracted project folder consists of Underwater propagation losses and device range example files.
2. How to import the workspace is explained in section 4.9.2 in NetSim User Manual.

Network setup

- The following network diagram illustrates what the NetSim UI displays when you open the example configuration file.

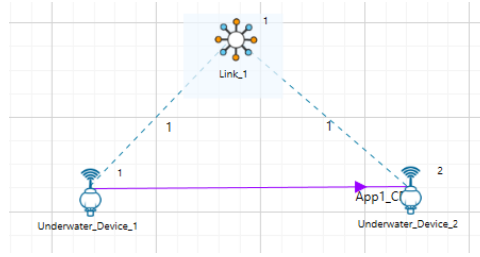


Figure 4-8: Network Scenario

- Click on link, expand the right-side property panel and set the Channel characteristics as Pathloss Only.
- Click on Underwater Device 1, expand the right-side property panel change the following parameters,

Table 4-7: Device Properties

Device Properties > Physical Layer	
Source Level ()	190.8, 187.78, 183.81
Data Rate (kbps)	20
Modulation Technique	QPSK, BPSK, FSK, 16QAM, 64QAM, 256QAM

- Configure a CBR Application from Source ID as 1 and Destination ID as 2 from set traffic window present in the ribbon at the top with Default Properties.
- Enable packet trace and Acoustic Measurements Log under Configure report tab as shown in Figure 4-3.
- Run the Simulation for 1000 sec.

Analytical computations

In the Thorp model, the dB/km attenuation is given by

$$10 \log_{10}(\alpha(f)) = \begin{cases} 0.11 \times \frac{f^2}{1 + f^2} + 44 \times \frac{f^2}{4100 + f^2} + 2.75 \times 10^{-4} \times f^2 + 0.003 & f \geq 0.4 \text{ kHz} \\ 0.002 + 0.11 \times \frac{f^2}{1 + f^2} + 0.011 \times f^2 & f < 0.4 \text{ kHz} \end{cases} \quad (31)$$

For this example, substituting $f = 20$, we get $10 \log_{10}(\alpha(f)) = 4.133 \text{ dB/km}$, we see that the total pathloss is

$$10 \log A(d, f) = k \times 10 \log(d_m) + d_{km} \times 10 \log \alpha(f) \quad (32)$$

Using input parameters K (spread coefficient) = 2, $f = 20 \text{ kHz}$ and distance between the source and destination, $d = 18 \text{ km}$, and we get the total transmission loss, TL , as

$$TL = 10 \log A(d, f) = 159.51 \text{ dB} \quad (33)$$

Next, we turn to noise level NL . The turbulence, shipping, wind, and thermal, noise level in dB is given by

$$10 \log N_t(f) = 17 - 30 \log(f) \tag{34}$$

$$10 \log N_s(f) = 40 + 20 \times (s - 0.5) + 26 \log f - 60 \times \log(f + 0.03) \tag{35}$$

$$10 \log N_w(f) = 50 + 7.5 \times \sqrt{w} + 20 \log f - 40 \log(f + 0.4) \tag{36}$$

$$10 \log N_{th}(f) = -15 + 20 \log f \tag{37}$$

Substituting $f = 20 \text{ kHz}$, shipping factor $s = 0.5$, surface windspeed $w = 0 \text{ m/s}$, we get $N_t = -22.03 \text{ dB}$, $N_s = -4.27 \text{ dB}$, $N_w = 23.63 \text{ dB}$, and $N_{th} = 11.02 \text{ dB}$. As explained in section 3.1.4 we see that wind noise has the most impact. After adding these noises in the linear scale and then converting back to dB , Total noise, $N_{Total}^{dB} = 23.87$. From the passive sonar equation

$$SNR = SL - TL - (NL - DI) \tag{38}$$

Substituting we get

$$SNR = 190.80 - 159.51 - (23.87 - 0) = 1.41 \text{ dB} \tag{39}$$

Results: Packet Error Rate vs Distance

For the above SNR, we plot PER vs. distance for different modulation schemes given default packet size of 14B.

$$PER = \frac{\text{No. of errored packets}}{(\text{No. of errored packets} + \text{No. of received packets})} \tag{40}$$

No. of errored packets can be obtained from link metrics and No. of received packets can be obtained from application metrics of the results dashboard as shown in the image below.

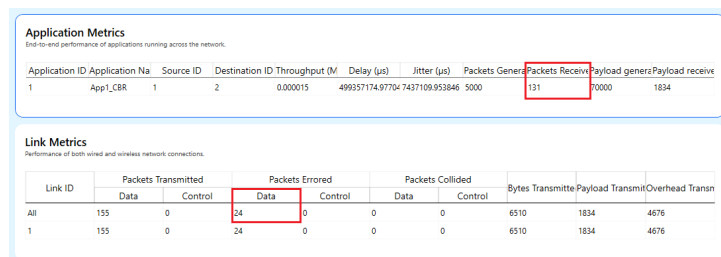
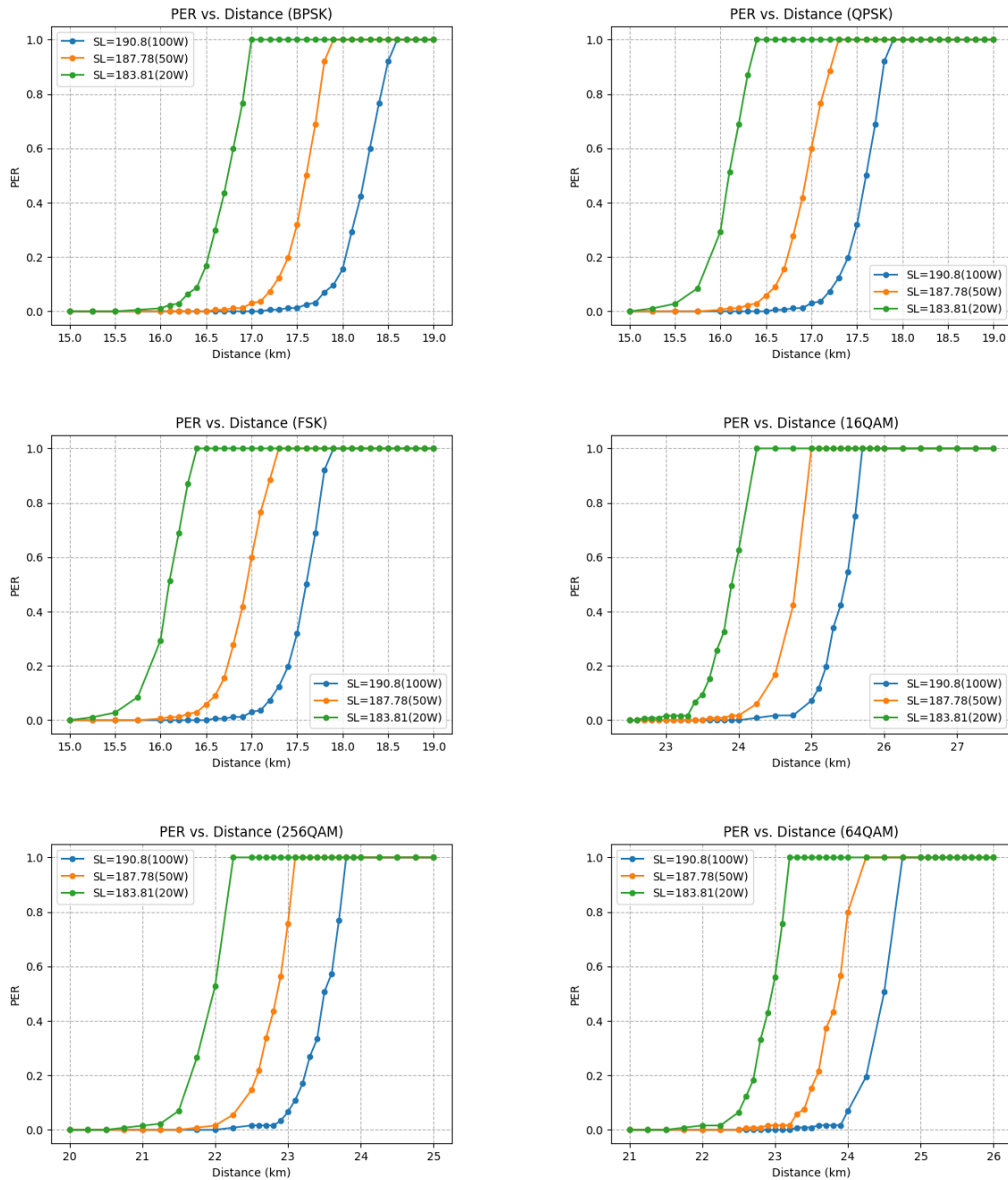


Figure 4-9: Result Dashboard window.

Table 4-8: *PER values for different modulations and distances.*

Distance (m)	Source Level (dB/ μ Pa)	Modulation	Pkts Received	Pkts Errored	PER
18000	183.81	FSK	0	19	1
18000	183.81	BPSK	0	19	1
18000	183.81	QPSK	0	19	1
18000	187.78	FSK	0	19	1
18000	187.78	BPSK	0	19	1
18000	187.78	QPSK	0	19	1
18000	190.8	FSK	0	19	1
18000	190.8	BPSK	131	24	0.154839
18000	190.8	QPSK	0	19	1
23000	183.81	16QAM	119	2	0.016529
23000	183.81	64QAM	32	41	0.561644
23000	183.81	256QAM	0	13	1
23000	187.78	16QAM	121	0	0
23000	187.78	64QAM	119	2	0.016529
23000	187.78	256QAM	7	22	0.758621
23000	190.8	16QAM	121	0	0
23000	190.8	64QAM	121	0	0
23000	190.8	256QAM	113	8	0.066116



Generally, range is defined as the Tx-Rx distance at which the PER is 10%. From these plots we can determine a device’s range. In summary, we see how the device range is dependent on Source Level, Noise, MCS and packet size.

4.3 s-Aloha performance with multiple transmit nodes

Open NetSim and Select Examples → Underwater Acoustic Network → s-Aloha performance with multiple transmit nodes and then click on the tile in the middle panel to load the example as Figure 4-10.

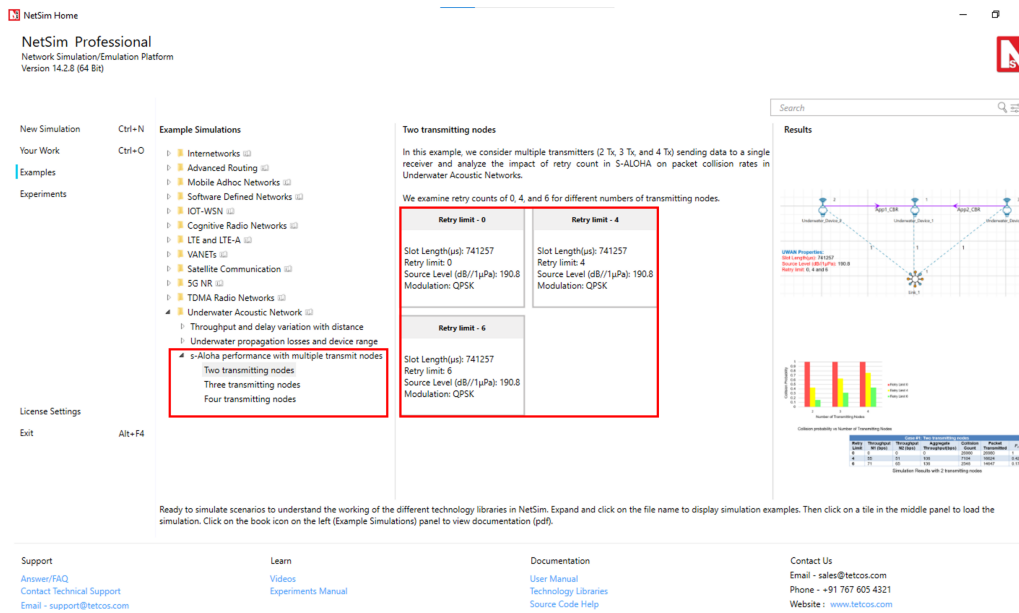


Figure 4-10: List of scenarios for the example of s-Aloha performance with multiple transmit nodes.

Network setup

We consider three scenarios as shown in the figure below, with 2, 3 and 4 transmitting nodes.

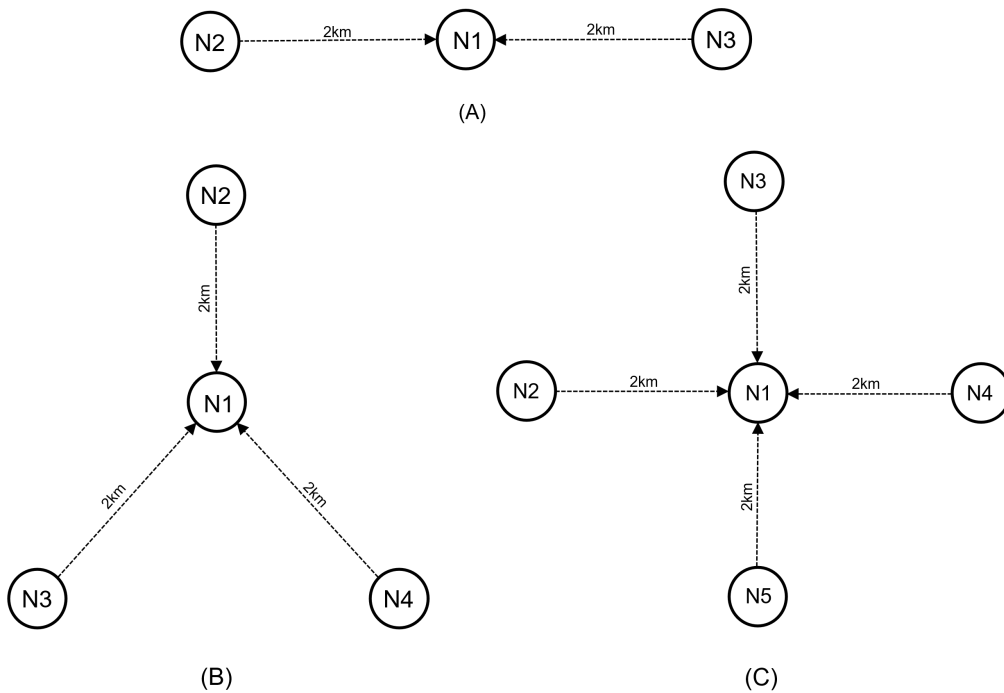


Figure 4-11: Simulation scenarios with 2 transmitting nodes in (A), 3 transmitting nodes in (B) and 4 transmitting nodes in (C). In all cases there is a single receiver.

Properties

Then we set the UWAN device properties as shown below

Table 4-9: *UWAN Device Properties*

Device Properties	
Device > Interface (ACOUSTIC) > Datalink Layer	
Retry Limit	0, 4, 6
Slot Length (μs)	741257
Device > Interface (ACOUSTIC) > Physical Layer	
Source Level ()	190.8
Modulation	QPSK
Data Rate (kbps)	20

- Here, we set the Slot Time as 741257 μs , which is the ideal value of 731257 μs plus a guard interval of 10,000 μs
- Configure a CBR Application from the source nodes (2, 3, 4 and 5 per the cases) to the destination (Node 1) with a packet size of 14 bytes and Inter arrival time as 560000 μs from set traffic window present in the ribbon at the top.
- Enable packet trace and Acoustic Measurements Log under Configure report tab as shown in Figure 4-3.
- Run the Simulation for 10000 sec.

Results

We observe throughputs from network metrics and packets transmitted and packets collided from the Link Metrics. We compute collision probability as $P_c = \frac{\text{Collision Count}}{\text{Packet Transmitted}}$ and tabulate the results in the different cases.

Table 4-10: *Simulation Results with 2 transmitting nodes*

Case #1: Two transmitting nodes							
Retry Limit	Thru. N1 (bps)	Thru. N2 (bps)	Agg. Thru. (bps)	Collision Count	Pkt Tx	P_c	
0	0	0	0	26980	26980	1	
4	51	55	106	7104	16624	0.427	
6	65	71	136	2548	14647	0.173	

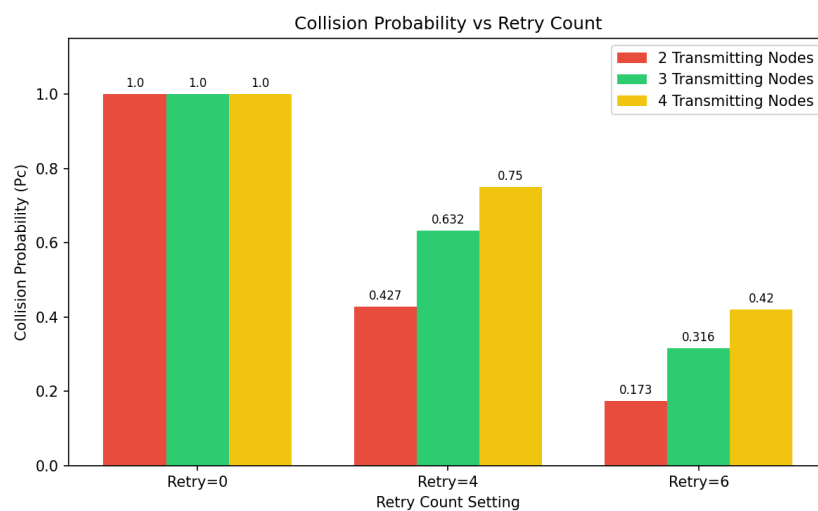
Table 4-11: *Simulation Results with 3 transmitting nodes*

Case #2: Three transmitting nodes							
Retry Limit	Thru. N1 (bps)	Thru. N2 (bps)	Thru. N3 (bps)	Agg. Thru. (bps)	Collision Count	Pkt Tx	P_c
0	0	0	0	0	40470	40470	1
4	26	26	27	79	12234	19348	0.632
6	43	41	37	121	4969	15726	0.316

Table 4-12: *Simulation Results with 4 transmitting nodes*

Case #3: Four transmitting nodes					
Retry Limit	Throughput N1 (bps)	Throughput N2 (bps)	Throughput N3 (bps)	Throughput N4 (bps)	Aggregate
0	0	0	0	0	
4	15	15	14	16	
6	28	27	26	26	

We carry out simulations with different settings of Retry Count. The final results are plotted below. When Retry count is set to zero, all packets collide even when just two nodes are transmitting. With retry count set to 0, the node attempts a packet transmission. If it fails, there is no retry and the packet is dropped. Recall, that in s-Aloha the transmitter does not back off before the first transmission attempt for a packet. With backlogged queues, the two transmitting nodes keep attempting at each slot. This leads to continuous collisions.

**Figure 4-12:** *Collision probability vs. number of transmitting nodes for different retry count settings.*

When the retry count is set to 4 (or 6) a transmitting node back off per the exponential backoff algorithm, before every retransmission. The back off algorithm is explained in section 3.2.3. Hence there is an element of randomness in packet transmissions at each slot. Nodes may or may not transmit. The probability of transmission at a particular slot reduces as the Retry Count is increased. Hence, we see lower collision probabilities for Retry count of 6.

4.4 Energy consumption analysis in underwater acoustic networks under varying traffic loads

4.4.1 Introduction

Efficient energy usage is important for underwater devices because the underwater environment imposes constraints on recharging options. Optimizing energy consumption is essential to ensure the longevity of the network.

Consider a practical underwater acoustic network comprising sensor nodes deployed in the ocean, which collect data and relay it to a master node. This master node aggregates the data, transfers it to a shore-based control center, and controls the sensor nodes. The network traffic consists of packetized data delivery from the sensor nodes to the master node.

In our project, we model such a network in NetSim. The setup includes master and sensor nodes distributed across 16 underwater devices, organized into three clusters (A, B, and C). Each cluster

contains sensor nodes responsible for data collection and transmission, with the master node managing data aggregation. The scenario is based on [9].

We analyse the energy consumption patterns of the sensors and the master node under different traffic loads.

Open NetSim and Select Examples → Underwater Acoustic Network → Energy consumption analysis in underwater acoustic networks under varying traffic loads and then click on the tile in the middle panel to load the example as shown in figure.

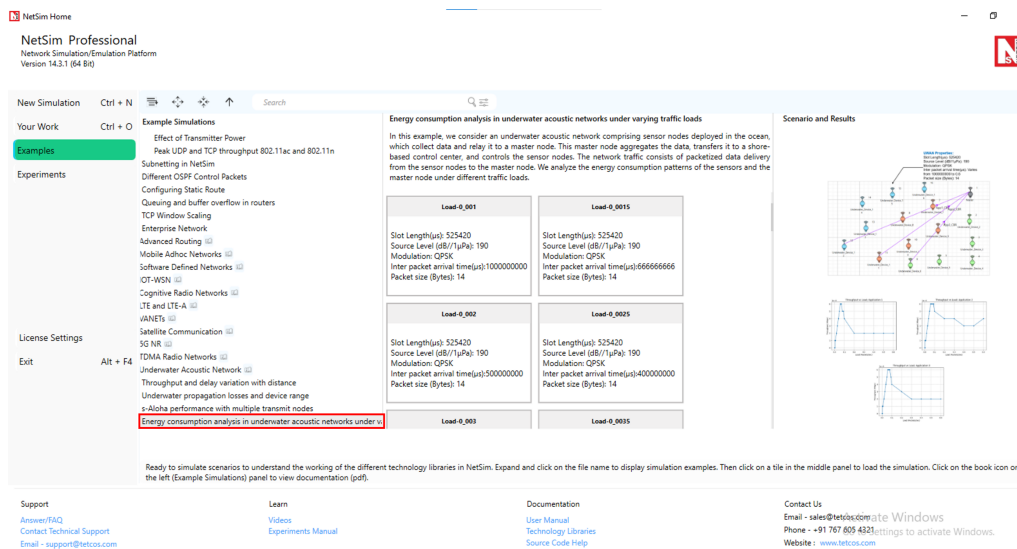


Figure 4-13: List of scenarios for the example of Energy consumption analysis in underwater acoustic networks

4.4.2 Network setup

The scenario comprises of 16 underwater devices, organized into three clusters (A, B, and C) and a master node.

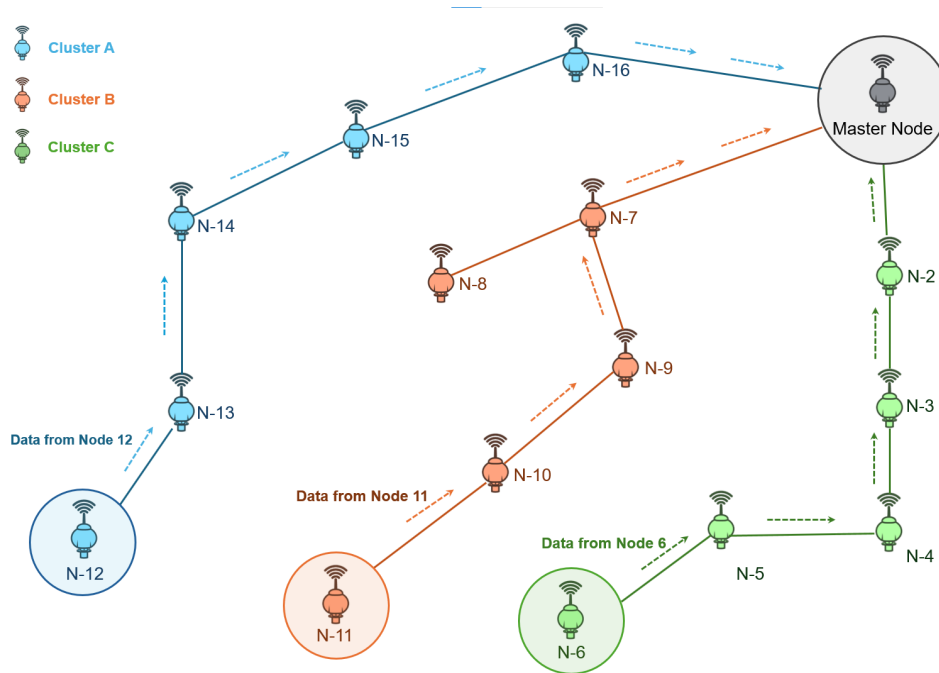


Figure 4-14: Scenario representing 3 different clusters and master node and data transmission from each cluster to the master node.

Cluster A: Underwater nodes 12, 13, 14, 15, 16.

Cluster B: Underwater nodes 11, 10, 9, 8, 7.

Cluster C: Underwater nodes 6, 5, 4, 3, 2.

Master Node: Node 1, responsible for collecting data from all the clusters.

The network is configured with static routing to ensure data transfer from sensor nodes to the master node. We assume an ideal channel with no pathloss.

Device Configuration

Table 4-13: Device properties set for this example

Device Properties	
Mac Layer	
Protocol	Slotted Aloha
Slot Length(μ s)	525420
Phy Layer	
Source Level (dB// 1μ Pa)	190
Modulation	QPSK
Data Rate (kbps)	20
Power	
Power source	Battery
Initial energy (mAH)	10416
Transmitting current (mA)	6250
Idle mode current (mA)	1.6
Voltage (v)	48
Receiving current (mA)	37.5

In our project, we use a data rate of 20 Kbps, whereas at the time of publication of reference [9], the modems supported data rates of 10s to 100s of bits per second. Consequently, the network in the current NetSim simulation can support a much higher traffic load. Therefore, while we expect different numerical results when comparing the outcomes, we anticipate observing similar trends to those reported in [9].

Slot Length Calculation This is a global parameter applicable to all UWAN devices. As a starting step, estimate the transmission time T_{tx} , which would be

$$T_{tx} (\mu s) = \frac{(L_{pkt} + OH) \times 8}{PHYRate} \tag{41}$$

where L_{pkt} is the application layer packet size, OH is the overheads of all layers which is equal to 28B, and $PHYRate$ is the data rate set in the PHY layer. Next, the propagation delay, Δ is computed as $\Delta = \frac{d}{c_{sound}}$, where d is the distance between the transmitter and the receiver. Thus, the ideal slot length should be

$$L_{slot} = \frac{(L_{pkt} + OH) \times 8}{PHYRate} + \frac{d}{C_{sound}} \tag{42}$$

In our scenario $L_{pkt} = 14B$ and $PHYRate = 20 Kbps$ which leads to $T_{tx} = 16,800 \mu s$. Then using $t = \frac{25}{10} = 2.5$, $z = 50$, and $S = 35$ - where t is one-tenth of the temperature of the water in degrees Celsius, z is the depth in meters and S is the salinity of the water - we get $c_{sound} = 2799.33 m/s$.

When the transmitter receiver distance is $d = 1423.79 m$, the propagation delay,

$$\Delta = \frac{1423.79}{2799.33} = 508618.13 \mu s. \tag{43}$$

Substituting all these, we see that the ideal slot length (when $d = 1423.79$) would be

$$L_{slot} = T_{tx} + \Delta = 16,800 + 508618.13 = 525420 \mu s \tag{44}$$

NOTE: The slot length is set based on the largest Tx-Rx distance i.e., from node 2 to Master node 1

Application Configuration

- Create a three CBR Application from the source nodes (12, 11, 6) to the Destination (Node 1) with a packet size of 14 bytes each and we will vary the inter arrival according to the load

Table 4-14: Application properties for different loads

Load (Pkt/sec)	Inter Arrival time	Load (Pkt/sec)	Inter Arrival time
0.001	100000000	0.0095	105263157
0.0015	666666666	0.01	100000000
0.002	500000000	0.02	50000000
0.0025	400000000	0.03	33333333
0.003	333333333	0.04	25000000
0.0035	285714285	0.05	20000000
0.004	250000000	0.06	16666666
0.0045	222222222	0.07	14285714
0.005	200000000	0.08	12500000
0.0055	181818181	0.09	11111111
0.006	166666666	0.1	10000000

Load (Pkt/sec)	Inter Arrival time	Load (Pkt/sec)	Inter Arrival time
0.0065	153846153	0.2	5000000
0.007	142857142	0.3	3333333
0.0075	133333333	0.4	2500000
0.008	125000000	0.5	2000000
0.0085	117647058	0.6	1666666
0.009	111111111		

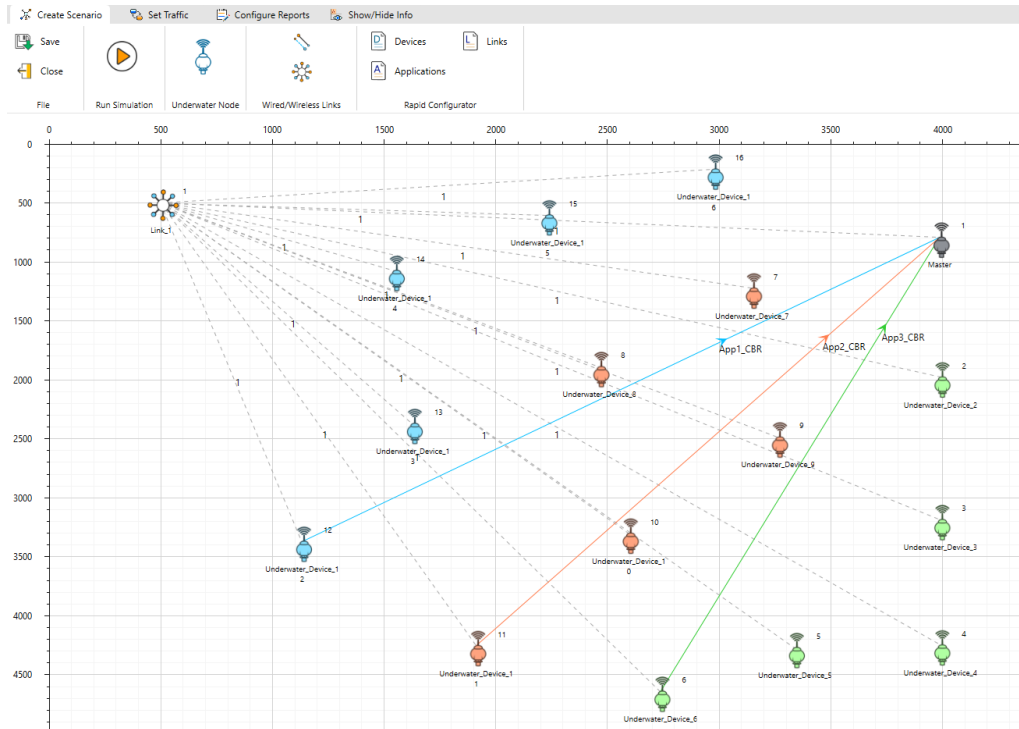


Figure 4-15: The network consists of 16 underwater devices connected via an acoustic link. Three applications are configured to send data from underwater sensors to the master node using static routes: App1 from Node 12 to Master Node 1 and App3 from Node 6 to Master Node 1.

4.4.3 Simulation results

Post simulation, click on the additional metrics in the simulation results window and scroll down for battery model metrics as shown below.

The screenshot shows the 'Simulation Results' window with the 'Additional Metrics' tab selected. The 'Battery model' table displays energy consumption and harvesting data for each device. The table has the following columns: Device Name, Initial energy(mJ), Consumed energy(mJ), Remaining Energy(mJ), Harvested Energy(mJ), Transmitting energy(mJ), Receiving energy(mJ), and Idle energy(mJ).

Device Name	Initial energy(mJ)	Consumed energy(mJ)	Remaining Energy(mJ)	Harvested Energy(mJ)	Transmitting energy(mJ)	Receiving energy(mJ)	Idle energy(mJ)
MASTER	179984800.000000	718113.134281	179916668.875720	0.000000	0.000000	26306.999174	691806.523107
UNDERWATER_DEVICE_2	179984800.000000	2277880.656493	179756999.343506	0.000000	1576238.955536	9501.688626	6921320.123211
UNDERWATER_DEVICE_3	179984800.000000	2287410.596653	179757389.403346	0.000000	1628342.791607	11023.271580	691972.542448
UNDERWATER_DEVICE_4	179984800.000000	2469759.214364	179735040.785636	0.000000	1970545.213363	7185.637111	692038.585389
UNDERWATER_DEVICE_5	179984800.000000	1918476.598568	179796323.401431	0.000000	1197805.951915	29652.996282	691217.649371
UNDERWATER_DEVICE_6	179984800.000000	5833651.368067	1794251148.631930	0.000000	4842166.380370	0.000000	691484.987957
UNDERWATER_DEVICE_7	179984800.000000	2044079.004938	179780720.995063	0.000000	1312019.272700	10994.754824	691064.976914
UNDERWATER_DEVICE_8	179984800.000000	0.000000	179984800.000000	0.000000	0.000000	0.000000	0.000000
UNDERWATER_DEVICE_9	179984800.000000	2538076.751255	179731723.248745	0.000000	1832459.137416	14866.024827	690691.409012
UNDERWATER_DEVICE_10	179984800.000000	3200345.825873	179664454.174122	0.000000	2477700.804674	32936.005676	690709.015723
UNDERWATER_DEVICE_11	179984800.000000	6179440.488670	1793705159.511328	0.000000	5489334.279930	0.000000	690206.209920
UNDERWATER_DEVICE_12	179984800.000000	5796787.252294	179406022.747707	0.000000	5106238.220506	0.000000	690309.912527
UNDERWATER_DEVICE_13	179984800.000000	3118378.271990	179666421.728611	0.000000	2396237.515488	20442.349872	690500.880919
UNDERWATER_DEVICE_14	179984800.000000	2115409.435210	179769390.564789	0.000000	1406905.277857	15389.425093	690514.732260
UNDERWATER_DEVICE_15	179984800.000000	2059639.167853	1797825160.832146	0.000000	1390310.520253	8455.831667	690872.815993
UNDERWATER_DEVICE_16	179984800.000000	2195214.809977	179769585.191071	0.000000	1498154.947414	8161.863122	690897.978992

Figure 4-16: Battery model metrics

The transmitting energy, receiving energy, idle energy, and total consumed energy for the Master node, Layer1 Node 7, and Layer2 Node 15 are tabulated in individual tables for different loads.

Table 4-15: *Tabulated results for Master node*

Load (Pkt/sec)	Transmit Energy (mJ)	Receive Energy (mJ)	Idle En- ergy (mJ)	Total Con- sumed Energy (mJ)
0.001	0	26307	691807	718113
0.0015	0	40796	716045	756841
0.002	0	55483	728281	783764
0.0025	0	68962	735374	804336
0.003	0	85278	739642	824919
0.0035	0	98271	742889	841159
0.004	0	111749	744856	856605
0.0045	0	125491	746883	872373
0.005	0	140663	748698	889361
0.0055	0	153426	748517	901943
0.006	0	169059	749059	918118
0.0065	0	182570	749340	931910
0.007	0	198170	750409	948580
0.0075	0	211879	749936	961815
0.008	0	223927	751157	975083
0.0085	0	235974	750280	986253
0.009	0	249913	750492	1000405
0.0095	0	266096	750124	1016220
0.01	0	281333	749353	1030686
0.02	0	575793	740784	1316577
0.03	0	854663	731155	1585818
0.04	0	1202139	715724	1917863
0.05	0	1619240	698524	2317764
0.06	0	2258239	670898	2929137
0.07	0	3088371	636044	3724415
0.08	0	3558266	616165	4174430
0.09	0	3645710	612425	4258136
0.1	0	3724541	608901	4333442
0.2	0	3488490	619132	4107622
0.3	0	3471500	619817	4091317
0.4	0	3377058	622000	3999057
0.5	0	3479548	619362	4098910
0.6	0	3542675	616830	4159505

Table 4-16: *Tabulated results for Layer 1, Node 7*

Load (Pkt/sec)	Transmit Energy (mJ)	Receive Energy (mJ)	Idle En- ergy (mJ)	Total Con- sumed Energy (mJ)
0.001	1312019	10995	691065	2014079
0.0015	1908392	15224	716275	2639890
0.002	2504764	20298	729141	3254203

Load (Pkt/sec)	Transmit Energy (mJ)	Receive Energy (mJ)	Idle En- ergy (mJ)	Total Con- sumed Energy (mJ)
0.0025	3339685	24527	735728	4099940
0.003	4174607	30447	740628	4945682
0.0035	4770979	35522	743810	5550311
0.004	5605901	42288	745971	6394159
0.0045	6202273	46516	748664	6997454
0.005	7037194	50745	749118	7837057
0.0055	7752841	54974	750409	8558223
0.006	8349214	60048	751573	9160835
0.0065	9064860	65969	751702	9882531
0.007	9780507	74426	752167	10607100
0.0075	10496154	78655	752933	11327742
0.008	11092527	89650	754046	11936222
0.0085	11688899	93878	753350	12536127
0.009	12285271	98953	753788	13138012
0.0095	12881644	103182	753777	13738603
0.01	13478016	107410	753323	14338750
0.02	27790954	219049	748891	28758894
0.03	42700264	317612	741797	43759672
0.04	59517965	434000	732687	60684652
0.05	76335667	584479	723131	77643277
0.06	108062678	712383	708987	109484048
0.07	147542531	1025897	686074	149254502
0.08	170443231	1274352	669363	172386946
0.09	201454596	1458335	653378	203566309
0.1	204078634	1622671	645366	206346672
0.2	236521293	2101952	617747	239240991
0.3	243319938	1984392	620982	245925312
0.4	229841922	1961101	625426	232428449
0.5	211473652	1905802	631998	214011452
0.6	255128111	2118476	612071	257858659

Table 4-17: *Tabulated results for Layer 2, Node 15*

Load (Pkt/sec)	Transmit Energy (mJ)	Receive Energy (mJ)	Idle En- ergy (mJ)	Total Con- sumed Energy (mJ)
0.001	1360311	8456	690873	2059639
0.0015	1943301	14093	716389	2673783
0.002	2526291	17475	728847	3272613
0.0025	3303611	20858	736534	4061003
0.003	3789436	24240	741228	4554905
0.0035	4469592	27059	744525	5241176
0.004	4955417	29877	746823	5732117
0.0045	5441242	34387	748685	6224314
0.005	6121397	37206	751498	6910101
0.0055	6898718	40024	751542	7690284

Load (Pkt/sec)	Transmit Energy (mJ)	Receive Energy (mJ)	Idle En- ergy (mJ)	Total Con- sumed Energy (mJ)
0.006	7481708	43970	751749	8277427
0.0065	8161863	48480	752431	8962775
0.007	8647688	51862	753131	9452682
0.0075	9133513	55245	753387	9942145
0.008	9910834	58063	754561	10723458
0.0085	10493824	60882	754372	11309078
0.009	10979649	64828	754200	11798678
0.0095	11562639	68210	754552	12385402
0.01	12048465	71593	754728	12874785
0.02	23513939	145440	752394	24411774
0.03	35076578	212523	747783	36036884
0.04	48874014	303846	741121	49918981
0.05	58292600	395733	734991	59423323
0.06	77508797	546810	724029	78779637
0.07	106500128	751442	707997	107959567
0.08	123932855	968475	688867	125590197
0.09	144988766	1032739	686546	146708050
0.1	158314046	1169160	676869	160160075
0.2	129284179	1241880	681804	131207862
0.3	136798000	1231169	679611	138708780
0.4	140626797	1258228	678243	142563269
0.5	167477286	1303889	669477	169450652
0.6	141795989	1167468	681776	143645234

4.4.4 Throughput and Packet collision count

The values for throughput of three applications and packets collided are listed below for different loads:

Table 4-18: *Tabulated results for throughput and packets collided.*

Load (Pkt/sec)	Throughput- 1 (Mbps)	Throughput- 2 (Mbps)	Throughput- 3 (Mbps)	Packets Collided
0.001	0	0	0	154
0.0015	0	0	0	233
0.002	0	0	0	306
0.0025	0	0	0	374
0.003	0	0	0	439
0.0035	0	0	0	511
0.004	0	0	0	578
0.0045	0.000001	0.000001	0.000001	642
0.005	0.000001	0.000001	0.000001	719
0.0055	0.000001	0.000001	0.000001	782
0.006	0.000001	0.000001	0.000001	843
0.0065	0.000001	0.000001	0.000001	913
0.007	0.000001	0.000001	0.000001	980
0.0075	0.000001	0.000001	0.000001	1052
0.008	0.000001	0.000001	0.000001	1125

Load (Pkt/sec)	Throughput- 1 (Mbps)	Throughput- 2 (Mbps)	Throughput- 3 (Mbps)	Packets Collided
0.0085	0.000001	0.000001	0.000001	1194
0.009	0.000001	0.000001	0.000001	1261
0.0095	0.000001	0.000001	0.000001	1331
0.01	0.000001	0.000001	0.000001	1396
0.02	0.000002	0.000002	0.000002	2805
0.03	0.000003	0.000003	0.000003	4167
0.04	0.000004	0.000004	0.000004	5747
0.05	0.000005	0.000005	0.000005	7542
0.06	0.000006	0.000006	0.000006	10088
0.07	0.000006	0.000006	0.000006	14228
0.08	0.000005	0.000006	0.000006	18428
0.09	0.000005	0.000006	0.000005	21346
0.1	0.000004	0.000005	0.000004	24555
0.2	0.000002	0.000004	0.000003	27718
0.3	0.000002	0.000004	0.000002	27771
0.4	0.000002	0.000003	0.000002	28000
0.5	0.000002	0.000003	0.000002	28074
0.6	0.000002	0.000004	0.000002	28143

Packets Collision Count

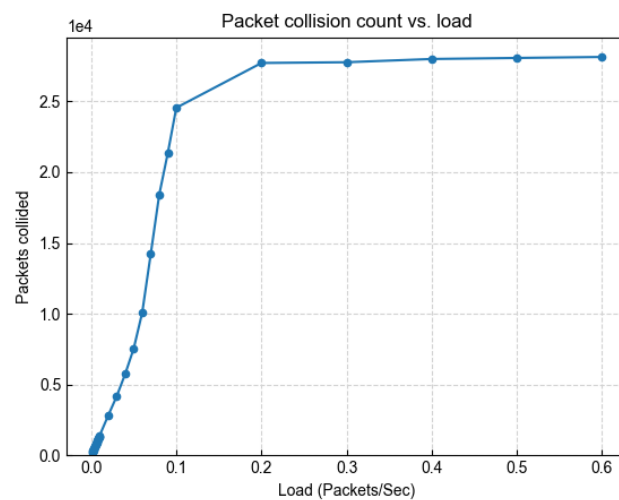


Figure 4-17: We observe the variation in collision count vs load, for this 16-node network running slotted aloha in the MAC layer.

As the load increases, the number of collisions rises sharply until it reaches a plateau. At low loads, the probability of collision is relatively low, and most packets are successfully transmitted. However, as the load increases, the probability of two or more packets being transmitted in the same time slot rises exponentially, leading to a rapid increase in collisions.

NetSim slotted Aloha implementation uses the exponential backoff algorithm when collisions occur. As collisions become frequent at high loads, nodes spend more time in backoff, effectively reducing their transmission attempts and stabilizing the collision rate.

Throughput

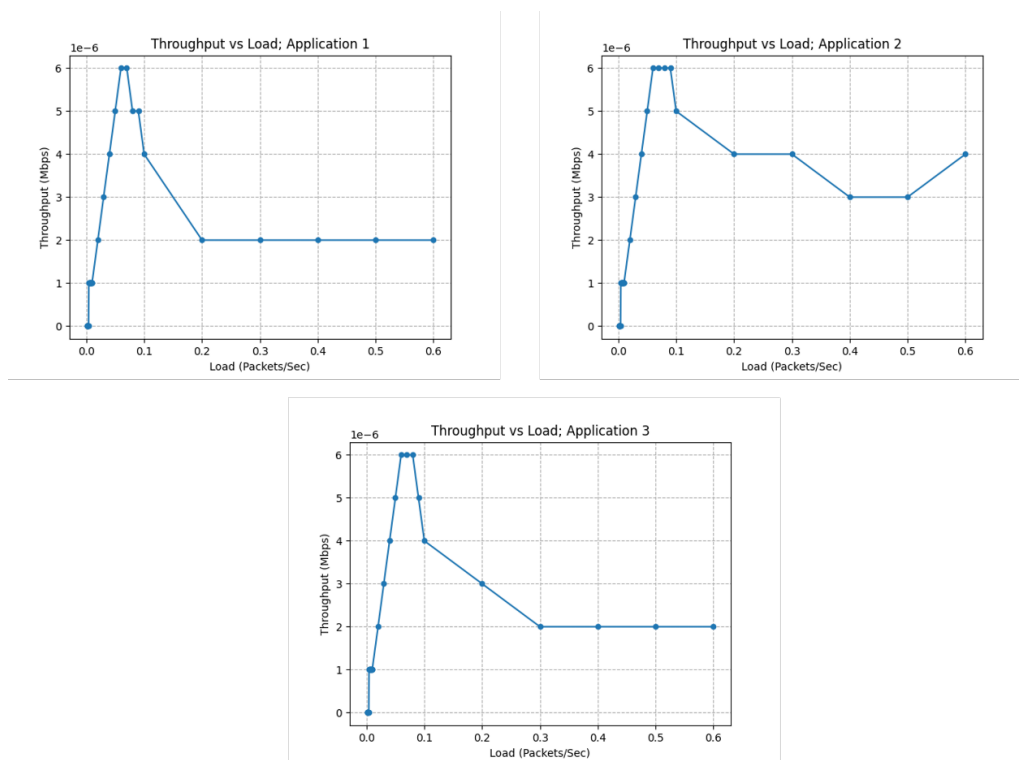


Figure 4-18: *Throughput plots for all three applications.*

The throughput behaviour can be explained by considering both the collision plot and the throughput graphs:

- **Initial increase:** At low loads, throughput increases as more packets are successfully transmitted with relatively few collisions.
- **Peak throughput:** The throughput reaches a maximum at an optimal load point (around 0.05–0.07 packets/sec). This represents the best balance between channel utilization and collision avoidance.
- **Sharp decline:** As load increases beyond the optimal point, we see a sharp rise in collisions (from the collision plot). This leads to a rapid drop in throughput because:
 - More transmission attempts result in collisions rather than successful transmissions.
 - Colliding packets waste channel capacity without contributing to throughput.
 - The exponential backoff algorithm causes nodes to wait longer before retransmitting, reducing overall transmission attempts.
- **Gradual stabilization:** The collision plot shows a plateau at higher loads, but throughput continues to decrease slightly or stabilize at a lower level. This occurs because:
 - The network is saturated with collisions.
 - Most transmission attempts fail due to collisions.
 - The backoff algorithm limits new transmission attempts.
 - The actual number of successful transmissions becomes a small fraction of the total load.
- **Differences between applications:**
 - Applications 1 and 3 use routes with 4 hops and show similar throughput patterns. They experience more throughput degradation at high loads as compared to application 2 due to longer paths.
 - Application 2 uses a route with only 3 hops and sees better throughput, at higher loads. This is because of the shorter path length, which reduces the overall collision probability because each additional hop increases the likelihood of collisions and packet loss.

- The throughput differences among applications stem from cross layer interactions of routing path lengths and the slotted Aloha MAC layer’s behaviour under varying loads.

Master Node 1 Energy Consumption See Figure 4-19

- The transmission energy from the master node will be zero because no transmission is occurring from the master node.
- As the load increases, the number of collisions initially rises rapidly but flattens out. Although the number of successfully received packets decreases, the node continues to receive collided packets. In the NetSim energy model, note that energy is expended in receiving these collided packets. However, once received, the node cannot decode the packets that have undergone collisions.
- The idle energy remains significant throughout all loads, though it slightly decreases at higher loads. This is because more energy is being consumed in receiving packets, leaving less time for the node to be idle.

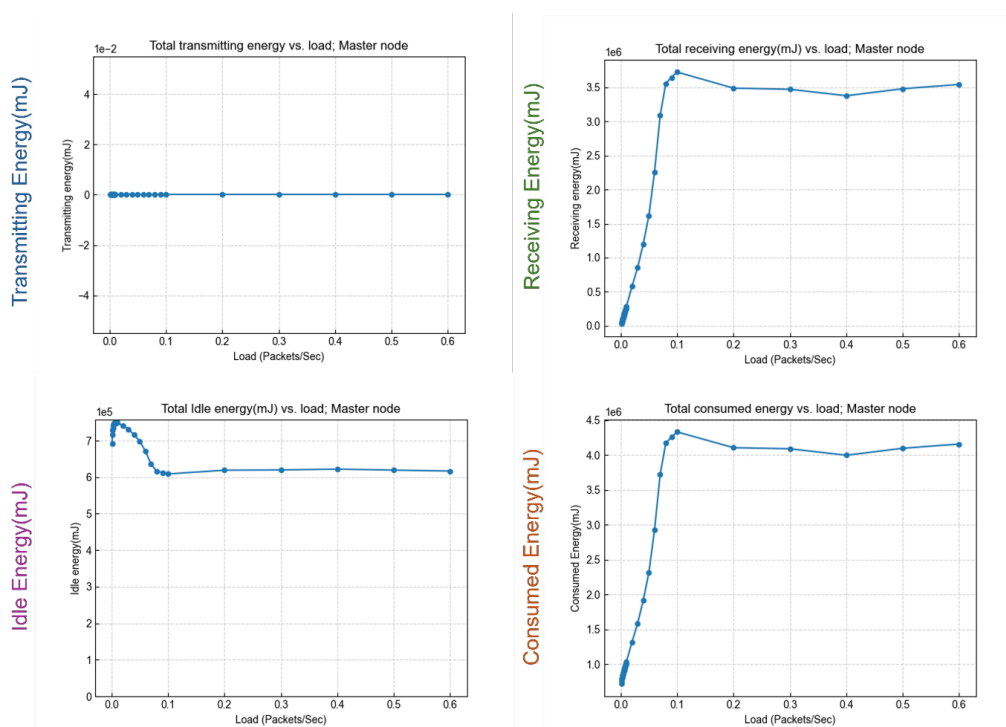


Figure 4-19: Energy Consumption Plots for the Master Node.

- The total consumed energy initially increases with network load, primarily due to the rise in receiving energy, and then flattens out.

Layer-1 Device – Node 7, Energy Consumption See Figure 4-20

- The transmitting energy for Layer 1 Node 7 increases significantly with the network load as it relays packets of Application 2 to the master node.
- The receiving energy also increases with load. This reflects its role in receiving packets that it must then forward to the master node.
- The idle energy remains relatively stable but shows a slight decrease at higher loads. This is due to the node spending more energy on transmission and reception rather than staying idle, at higher loads.

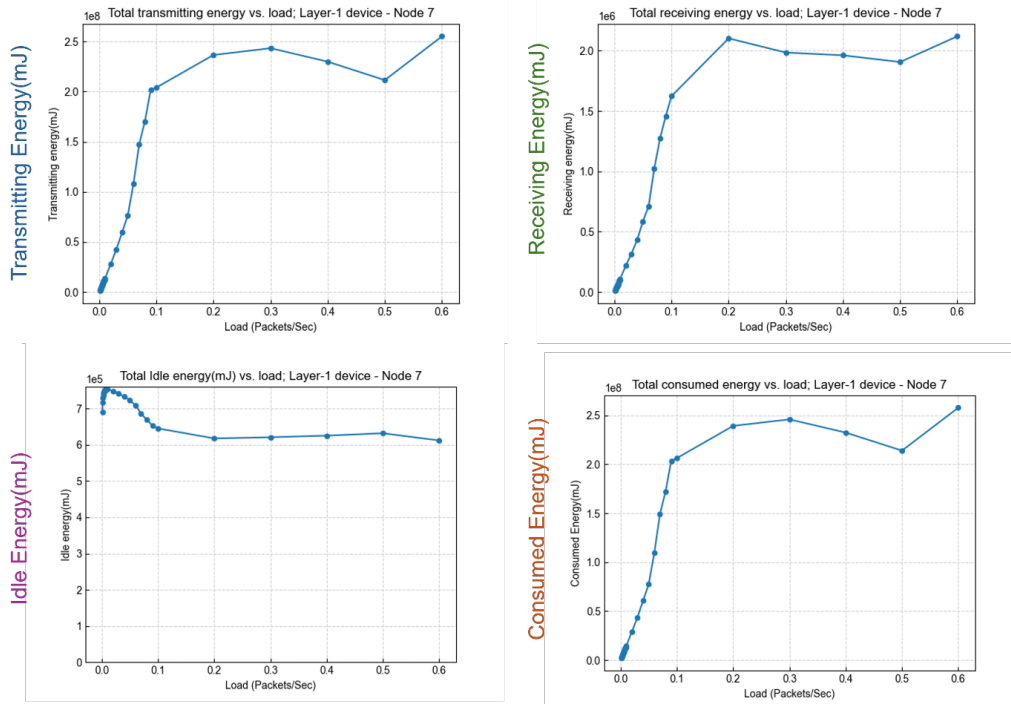


Figure 4-20: Energy Consumption Plots for the Layer1 Node 7

- The total consumed energy increases with the network load, driven by the substantial rise in both transmitting and receiving energies.
- These plots reflect Node 7’s active role in relaying traffic from outer layers to the master node.

Layer-2 Device – Node 15 Energy Consumption See Figure 4-21

- The curves depicted in the four panels in Figure 4-21 closely resemble those in Figure 4-20 with the only distinction being slightly lower values. This difference arises because: Node 15 serves as a relay for Application 1, while Node 7 relays for Application 2. Application 1 sees lower throughput compared to Application 2 due to its longer path (4 hops versus 3 hops). Consequently, Node 15 relays fewer packets than Node 7, resulting in reduced transmit and receive energy consumption. This, in turn, leads to lower total energy consumption for Node 15.

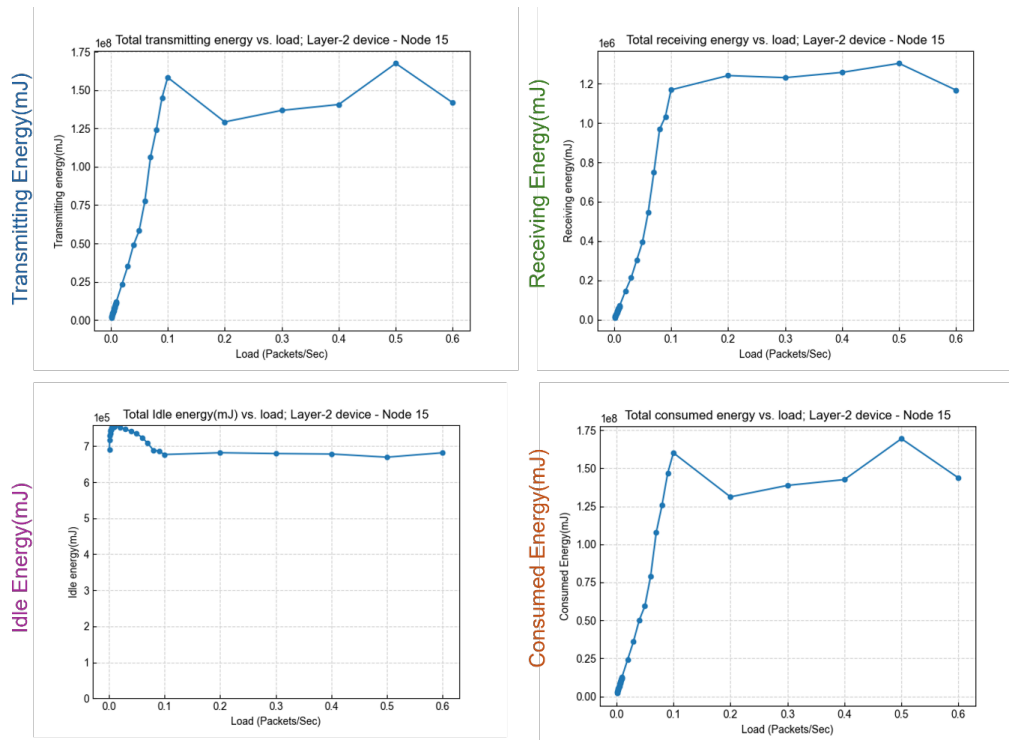


Figure 4-21: Energy consumption plot for a Layer-2 device, Node 15

5 Limitations

- Users cannot model buoy nodes, behaving as network sink(s) to collect data which can then be transmitted, via Radio Frequency (RF), to a nearby boat, or satellite
- Link layer ACKs are not modeled in s-Aloha
- There is no Guard time between slots in s-Aloha
- Doppler shift on account of transmitter and/or receiver motion is not accounted
- UWAN cannot connect to an “external” network; it operates stand alone.
- All devices are assumed to be time synchronized.
- Models for simulating multipath fading are not currently available.

6 References

- [1] A. B. Coppens, “Simple equations for the speed of sound in Neptunian waters,” 1981.
- [2] H. U. Yidliz, V. C. Gungor and B. Talvi, “Packet Size Optimization for Lifetime Maximization in Underwater Acoustic Sensor Networks,” *IEEE Transactions on Industrial Informatics*, 2019.
- [3] M. Stojanovic and J. Preisig, “Underwater Acoustic Communication Channels: Propagation Models and Statistical Characterization,” *IEEE Communications Magazine*, 2009.
- [4] D. E. Lucani, M. Medard and M. Stojanovic, “Capacity Scaling Laws for Underwater Networks,” 2012.
- [5] M. Stojanovic, “On the Relationship Between Capacity and Distance in an Underwater Acoustic Communication Channel,” in *WUWNet*, 2006.
- [6] J. L. J. M. J. a. L. P. S. Sendra, “Underwater Acoustic Modems,” *Sensors journal*, vol. 16, p. 11, 2016.
- [7] [Online]. Available: <https://www.l3harris.com/sites/default/files/2020-09/ims-maritime-datasheet-GPM%20300.pdf>.
- [8] R. J. Urick, “Principles of Underwater Sound, Peninsula Publishing,” 1983.
- [9] M. S. a. J. G. P. E. M. Sozer, “Design and Simulation of an Underwater Acoustic Local Area Network”.